

Nuclear Emulsion  
and  
Its Readout System

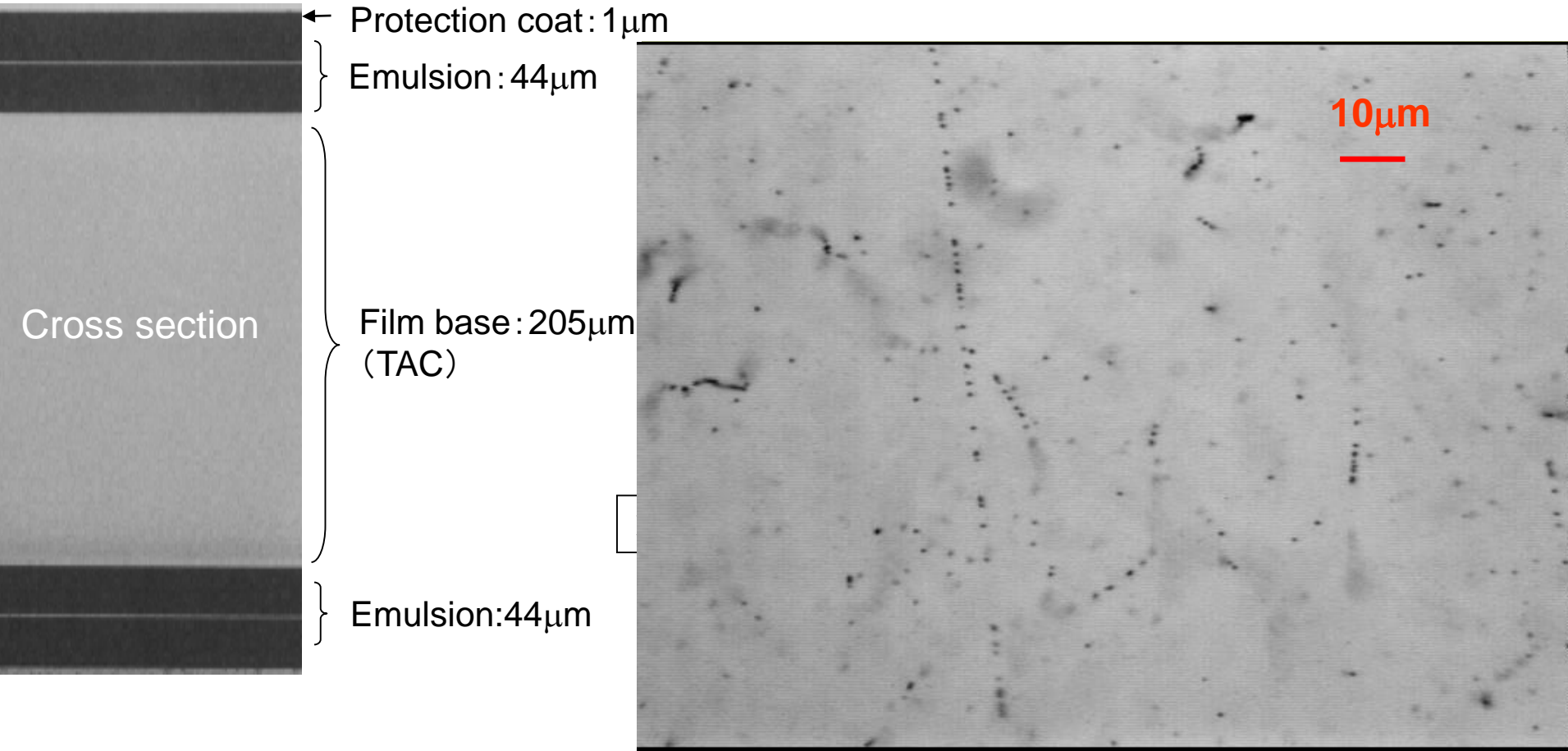
Toshiyuki Nakano  
Nagoya university

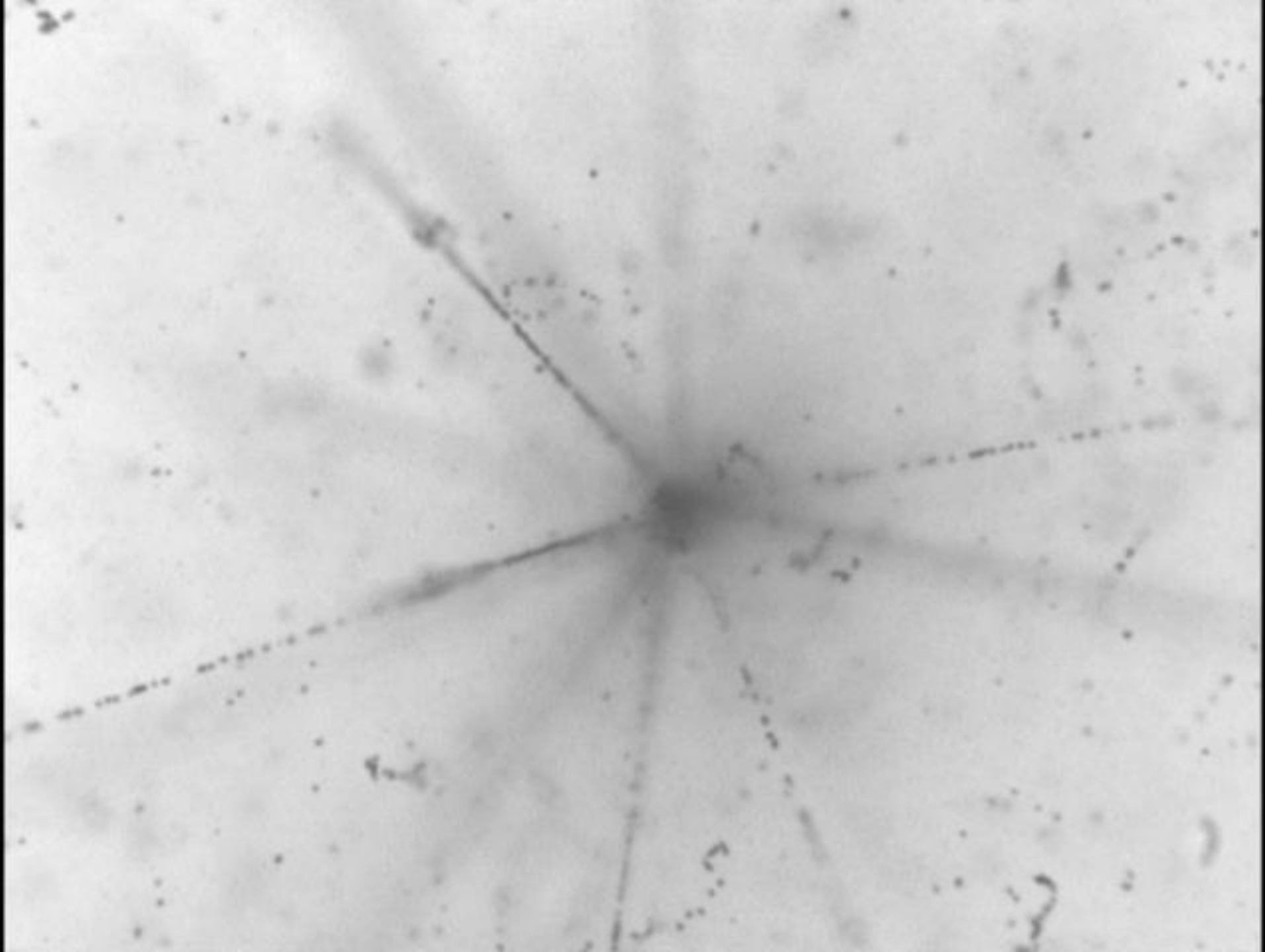
# Nuclear Emulsion Film

- Very high spatial resolution. ▪ Possible to record MIP's tracks

“OPERA film” is uniform, refreshable and mass producible.

~100,000m<sup>2</sup> are used in OPERA

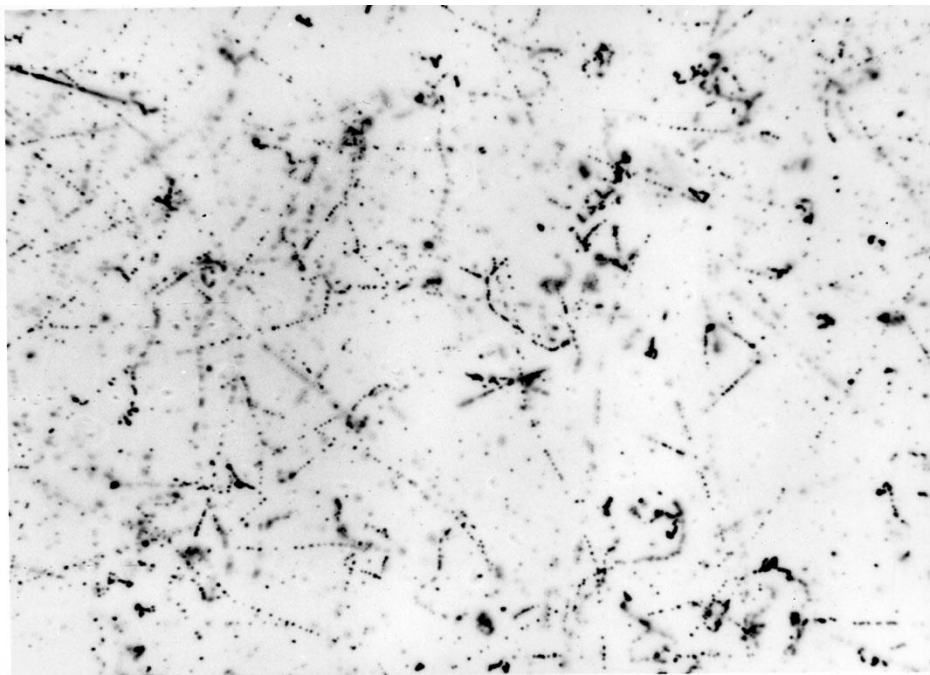




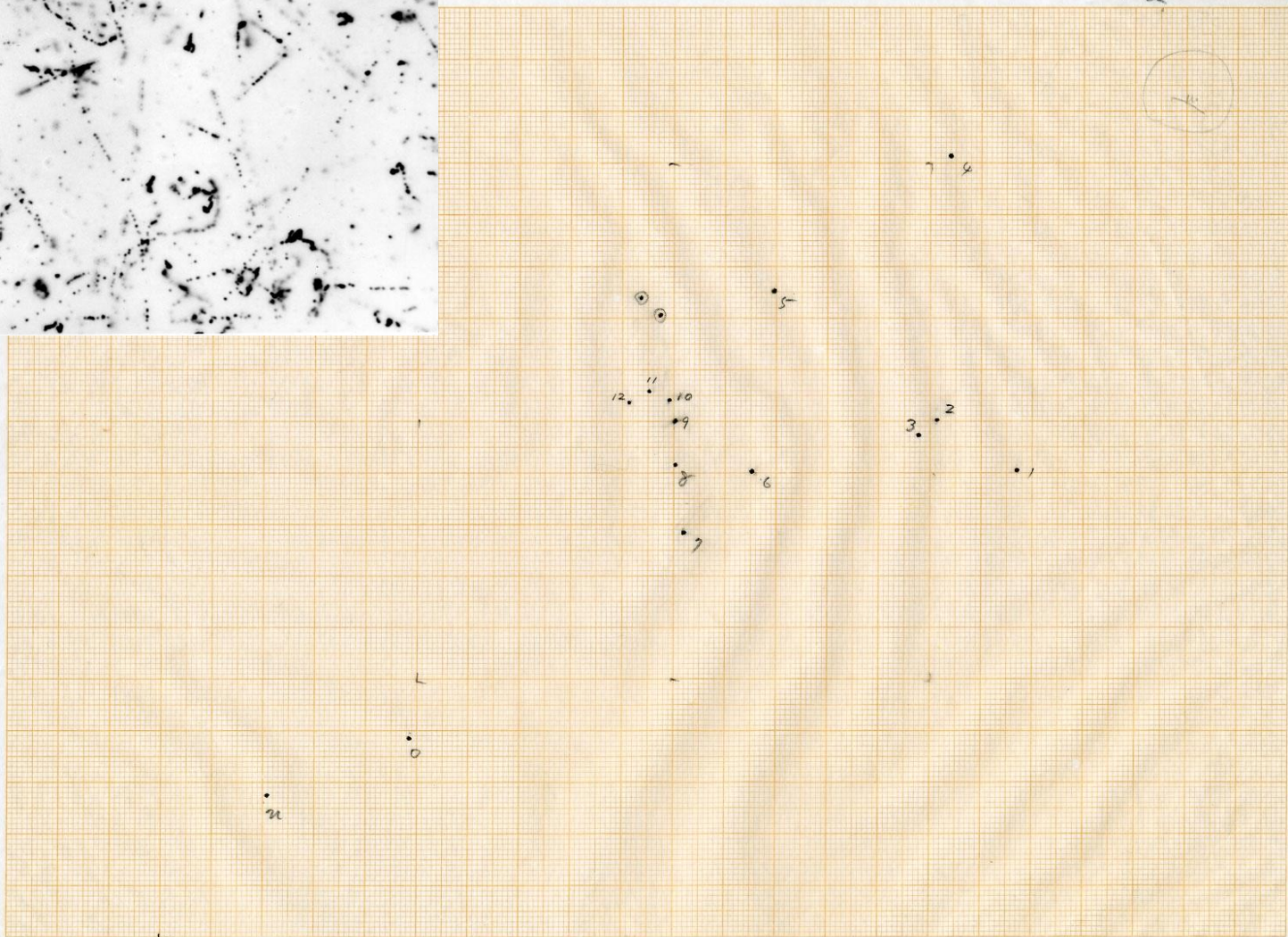
# Prof. Niu's effort

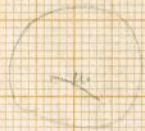
- 2-3 events / Half year
- Emulsion analysis by Eye and Hand





29表





4

5

10  
11  
12

2  
3

6

8

7

1

0

n

n

o

12  
11  
10  
9

8  
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4

3

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4

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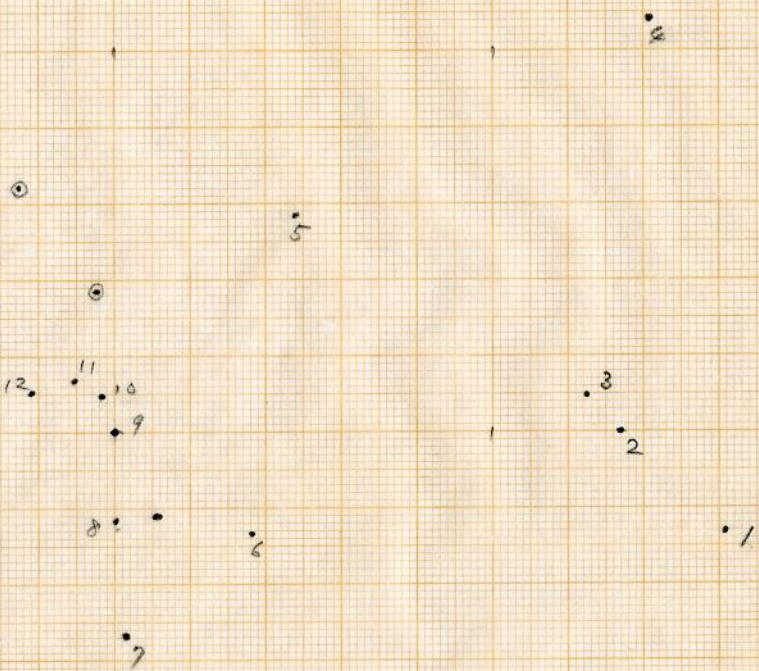
6

1

7

0

16



0

n



• 4

• 5

• 1

• 3

• 2

• 1

• 8

• 6

• 7

• 10

• 9

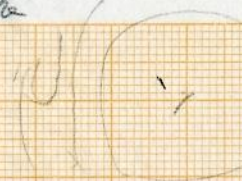
• 11

• 12

• 13

• 0

• 1



0

5

4

•

3

12

11

10

9

2

8

6

1

7

0

EVENT 6B-23

$(19 + 70)n$

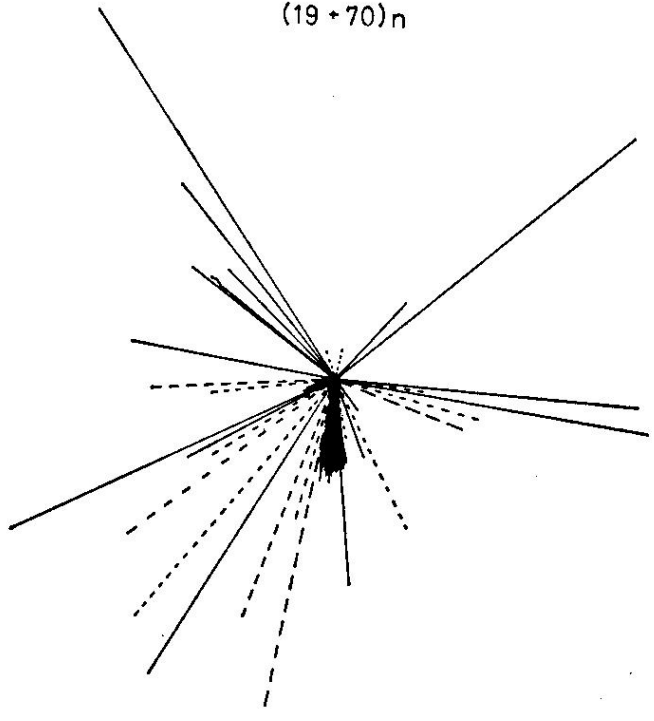


Fig. 1.

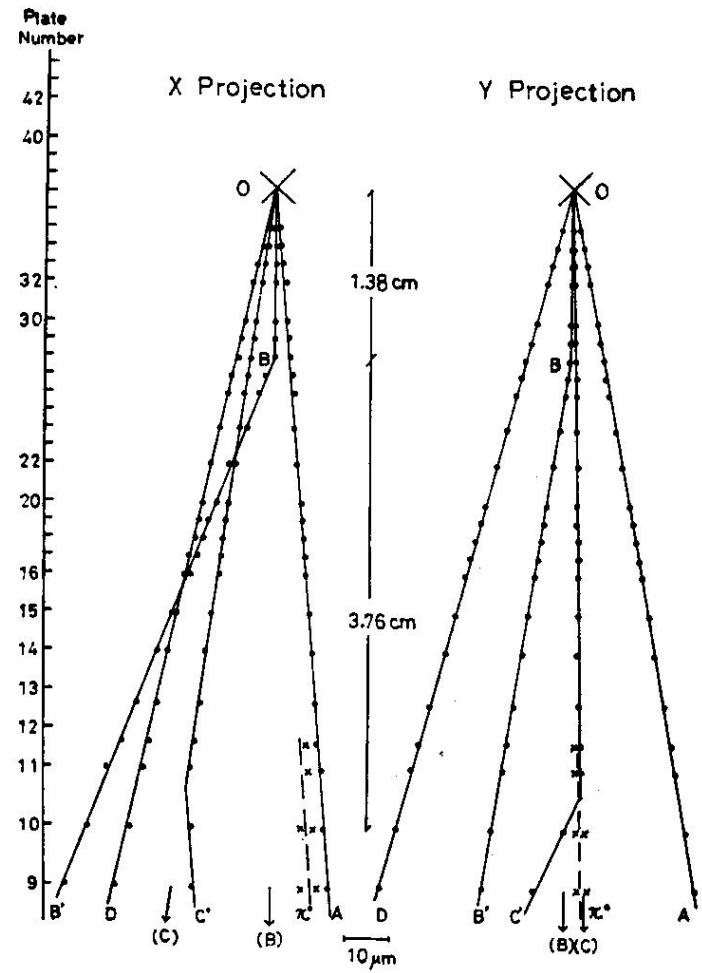


Fig. 3(a).

Fig. 3(b).

Plate  
Number

$\gamma$ - Projection

38

32

30

22

20

16

12

11

10

9

8

7

6

5

B

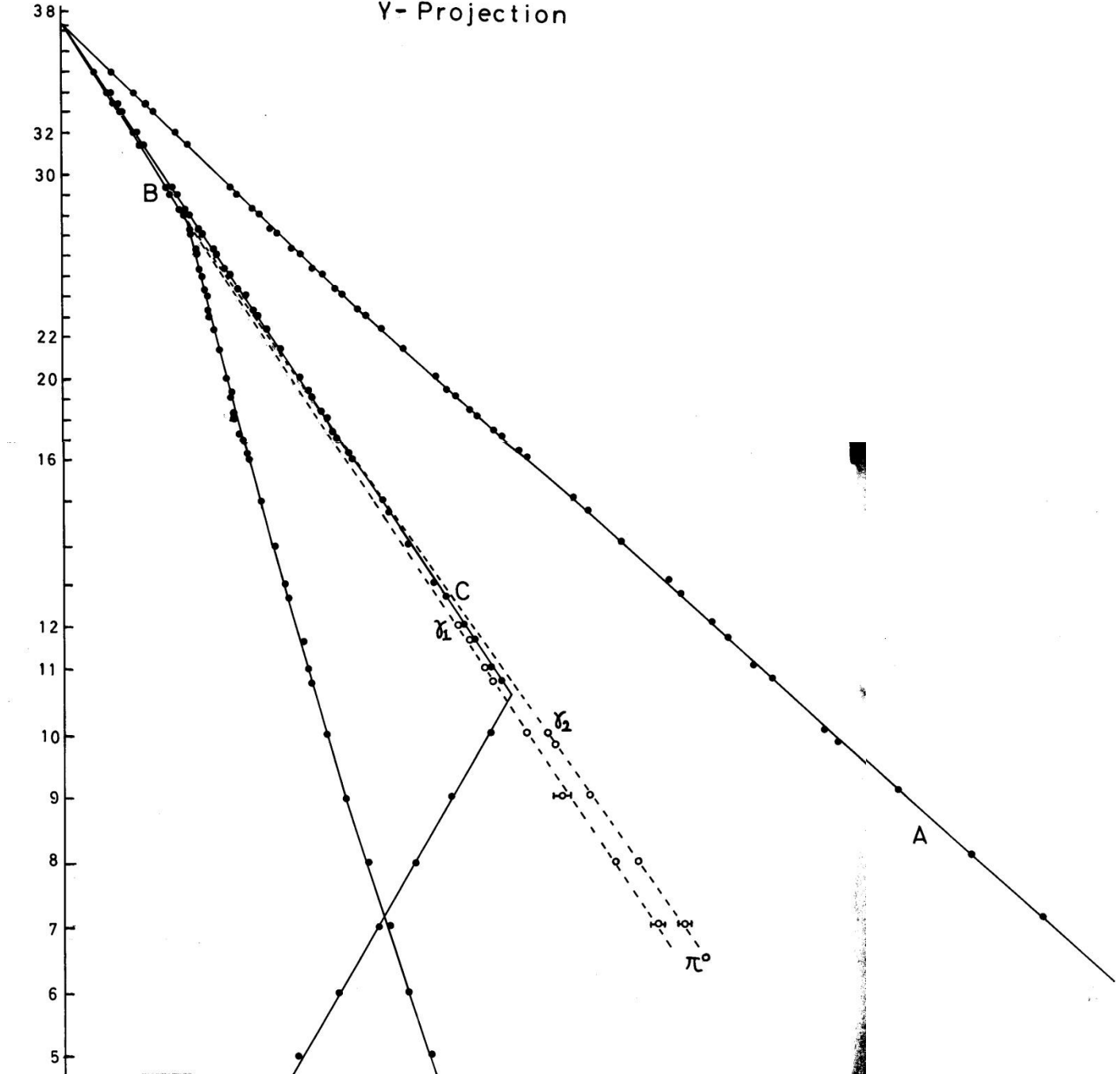
C

$\gamma_1$

$\gamma_2$

$\pi^0$

A

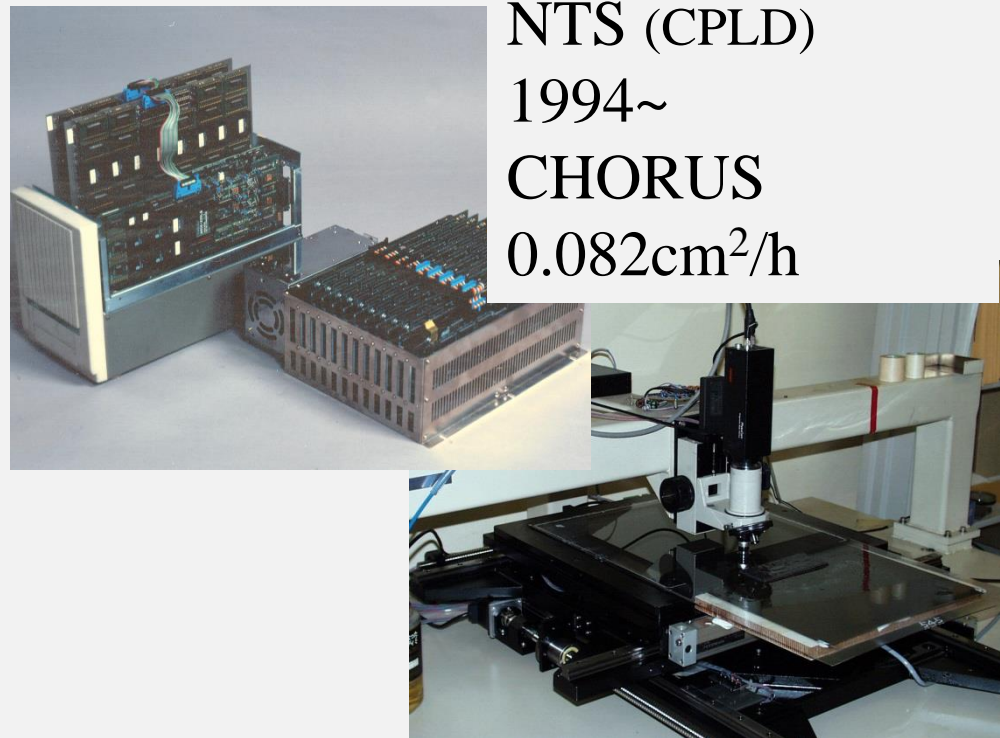


# Automated Emulsion Read-out system

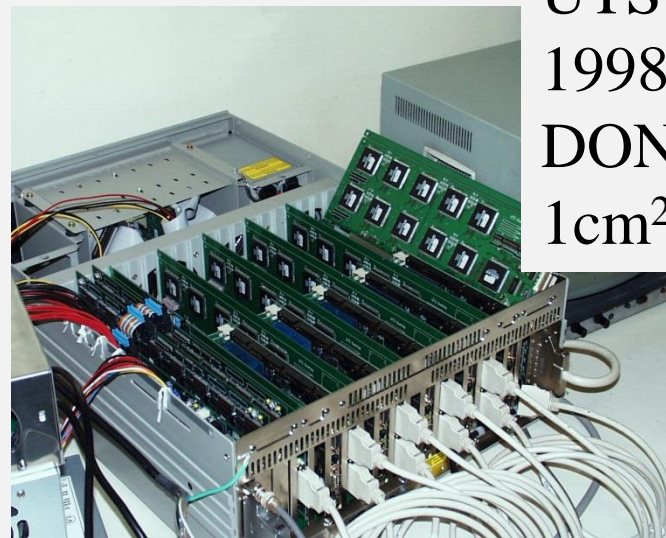
- Principle was proposed by K. Niwa in mid. 70s.
- The first system construction in 1983.
- The first application to real experiment in 1994.  
CHORUS (CERN WA95)
- The latest version “SUTS” was developed and applied to OPERA experiment.
  - The current speed of SUTS is  $72\text{cm}^2/\text{hrs}/\text{side}$

# History of emulsion readout system in Nagoya

NTS (CPLD)  
1994~  
CHORUS  
0.082cm<sup>2</sup>/h



UTS (FPGA)  
1998~  
DONUT  
1cm<sup>2</sup>/h

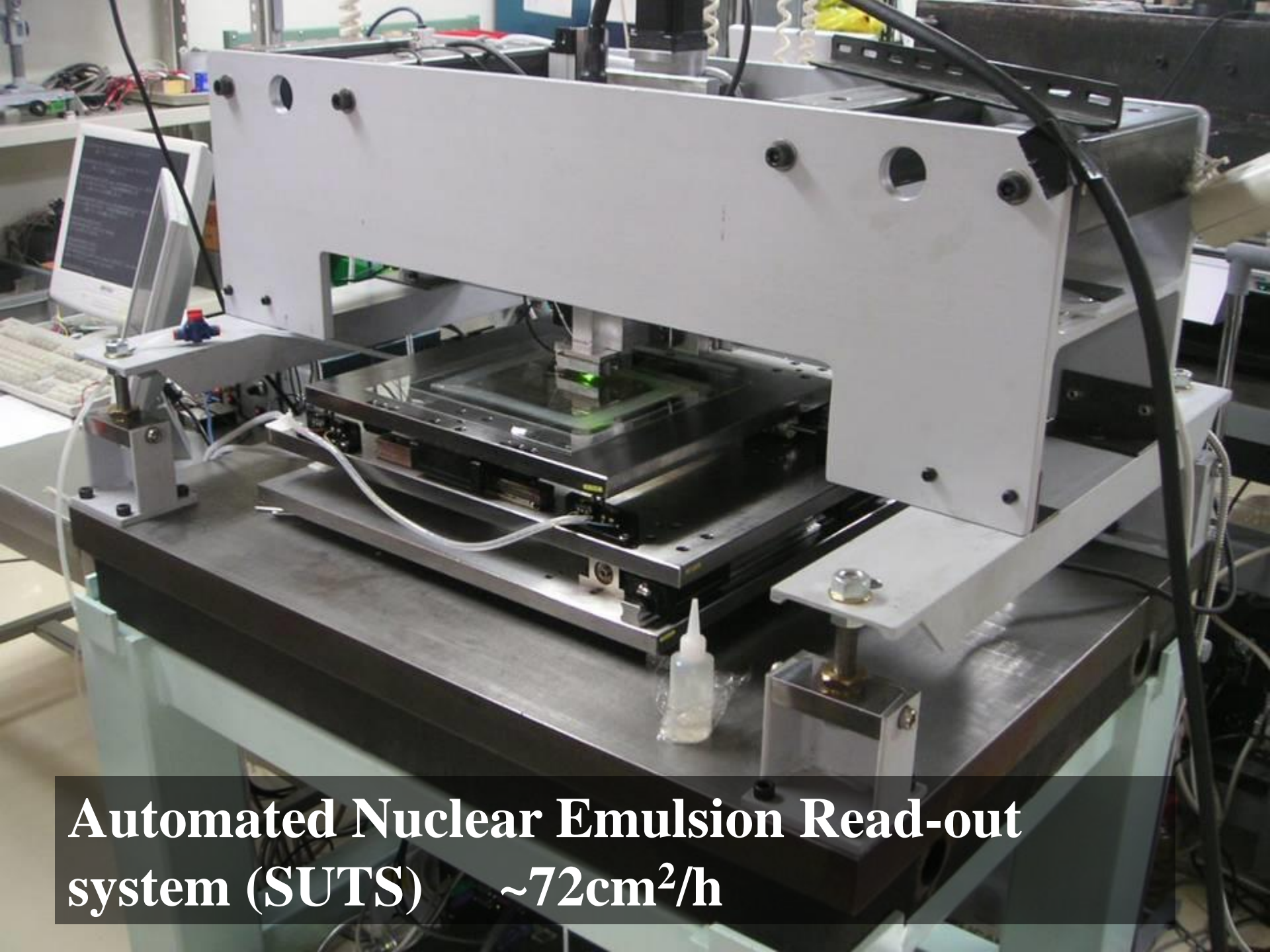


No picture

TS (TTL)  
1983~  
E653  
0.003cm<sup>2</sup>/h

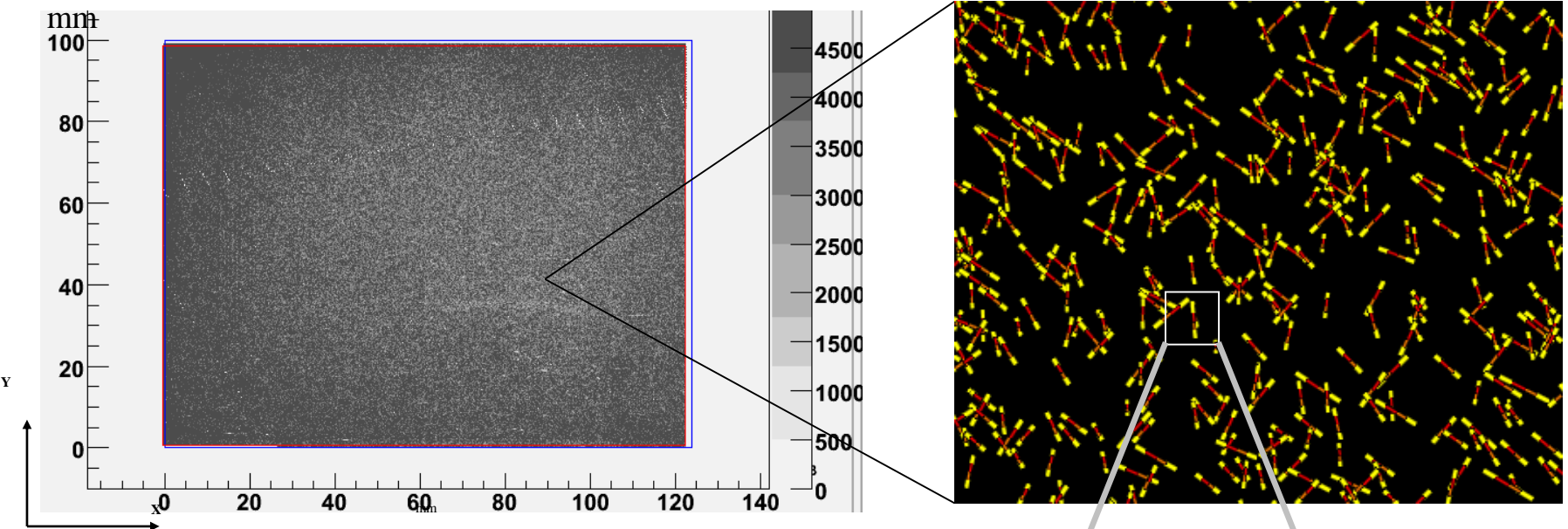
Each new system has enabled  
new experiment





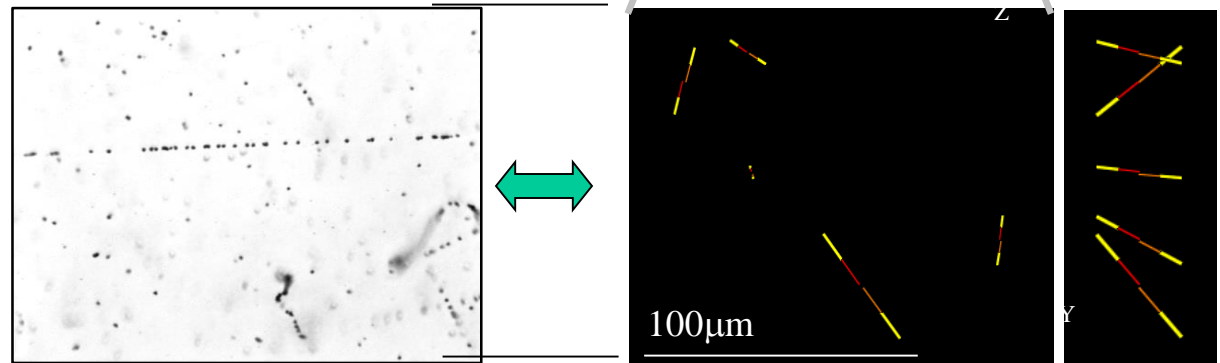
**Automated Nuclear Emulsion Read-out  
system (SUTS)  $\sim 72\text{cm}^2/\text{h}$**

# Output of Automated Emulsion Readout

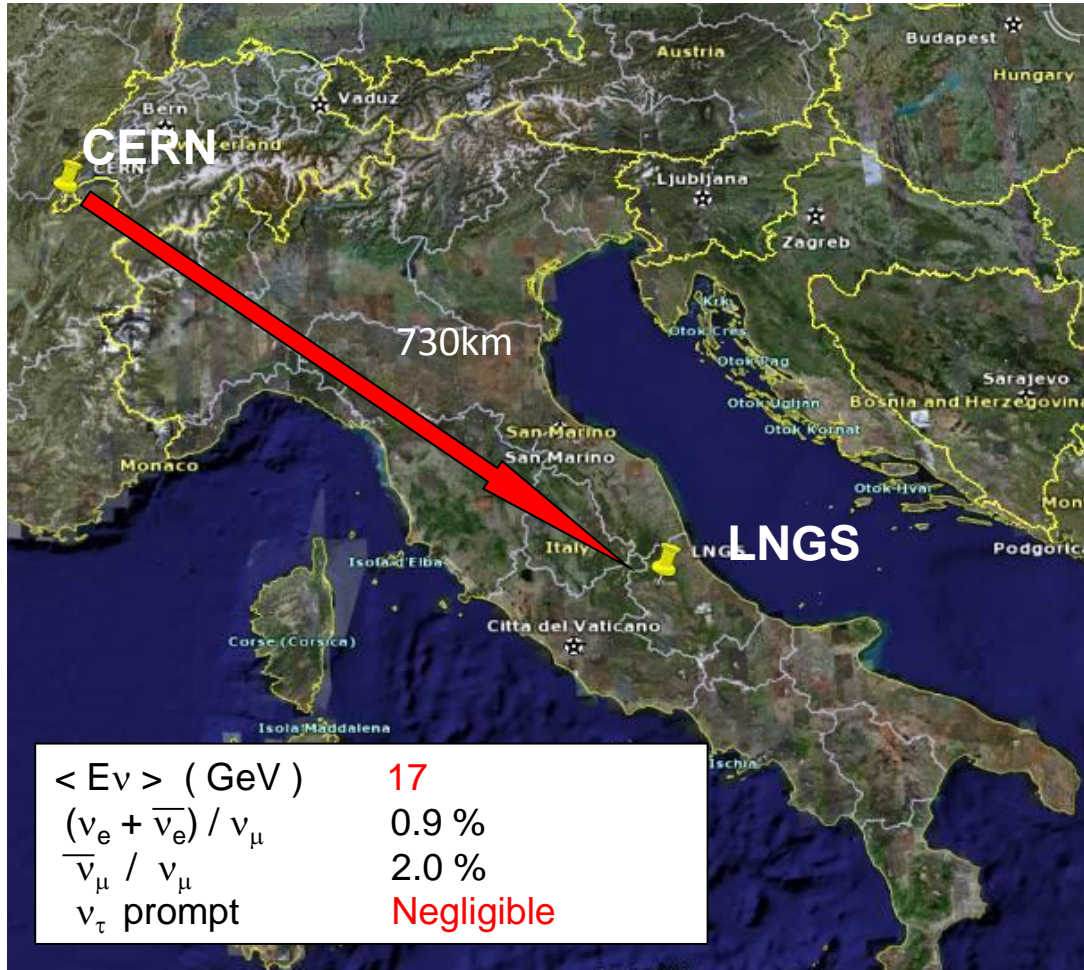


Position distribution of tracks  
(OPERAフィルム1枚全面、Total  $10^8$  tracks)

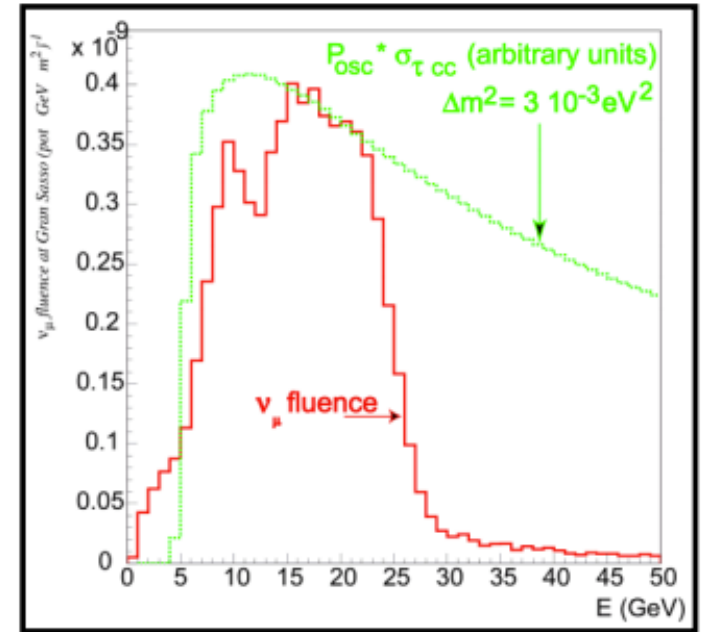
1 microscope view



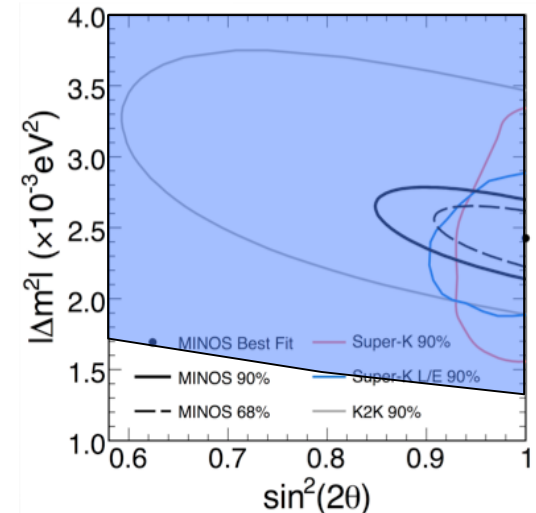
# OPERA $\nu_\mu \rightarrow \nu_\tau$ oscillation in appearance mode



CNGS Neutrino Beam



Covers the region indicated by Super-K, K2K & MINOS

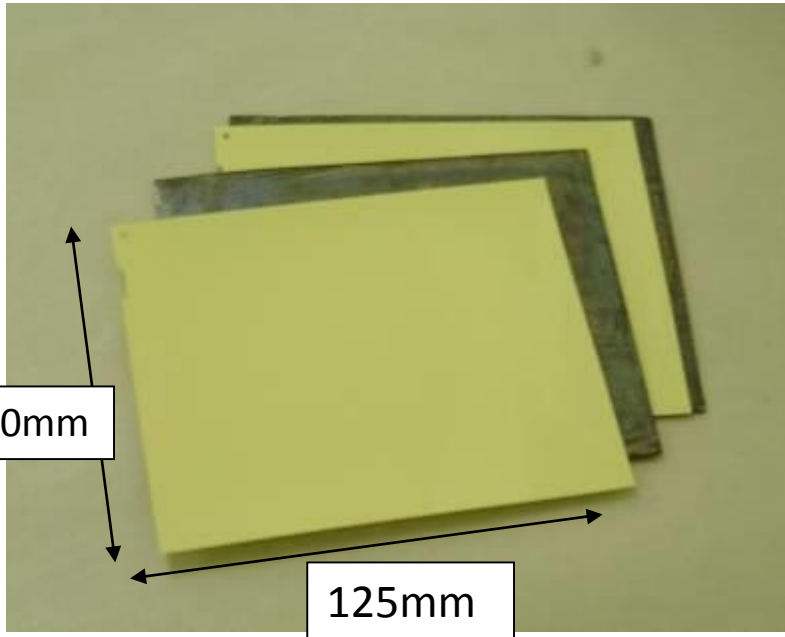
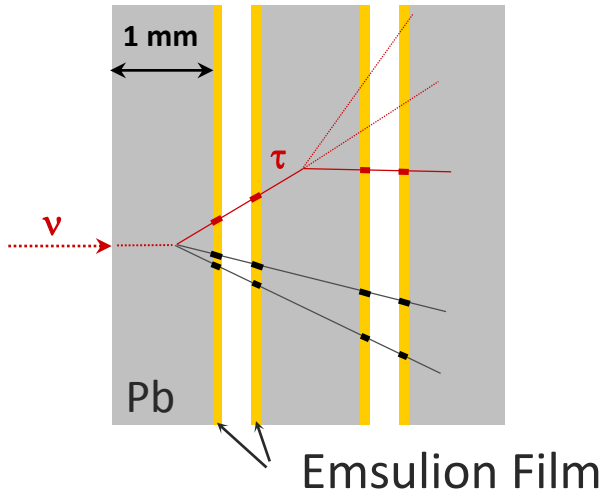


$$P(\nu_\mu \rightarrow \nu_\tau) \sim \sin^2(2\theta_{23}) \cdot \sin^2\left(1.27 \cdot \Delta m_{23}^2 \cdot \frac{L}{E}\right) \sim 1.6\%$$

$$\sin^2 2\theta_{23} = 1.0, \quad \Delta m_{23}^2 = (2.32) \times 10^{-3} \text{eV}^2$$

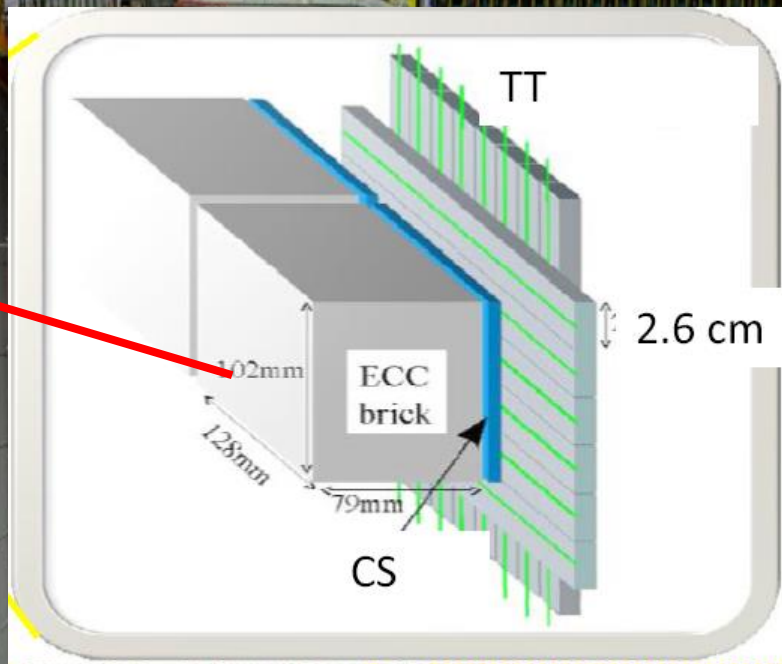
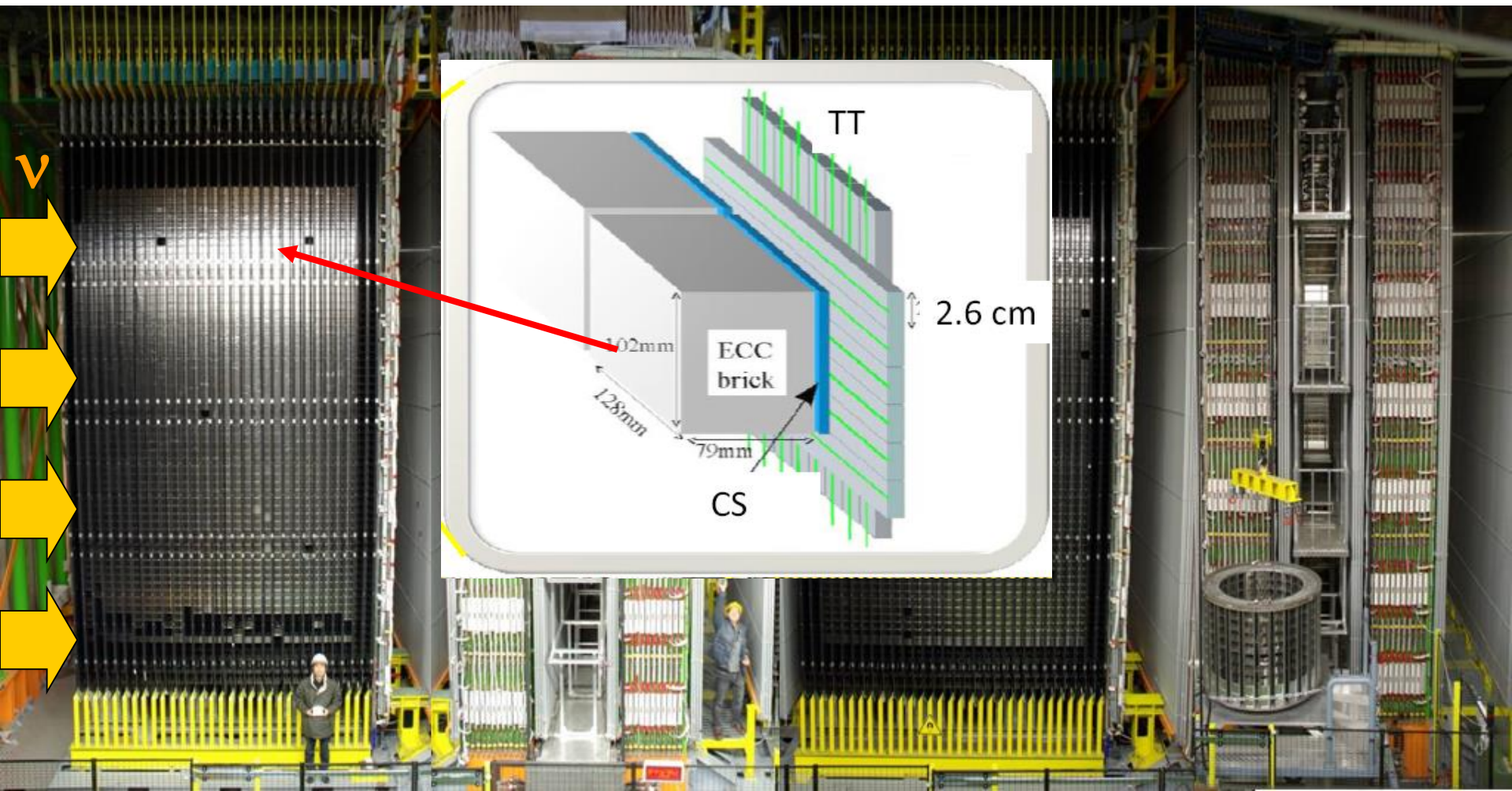
# OPERA ECC

Pb Plate (1mm) / Emulsion Film Sandwich

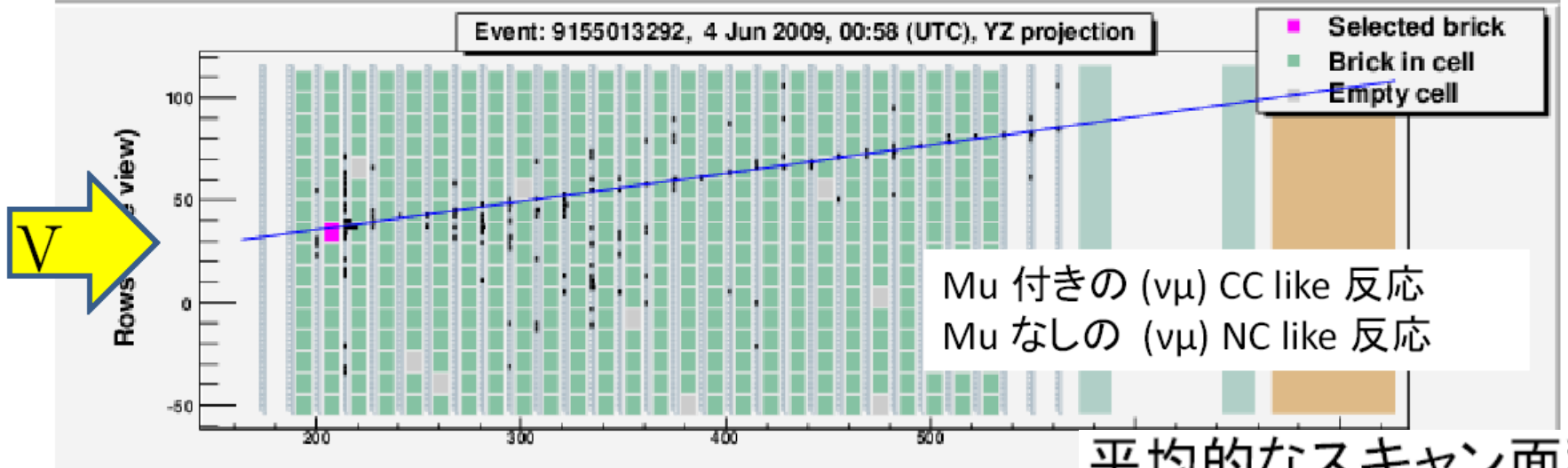
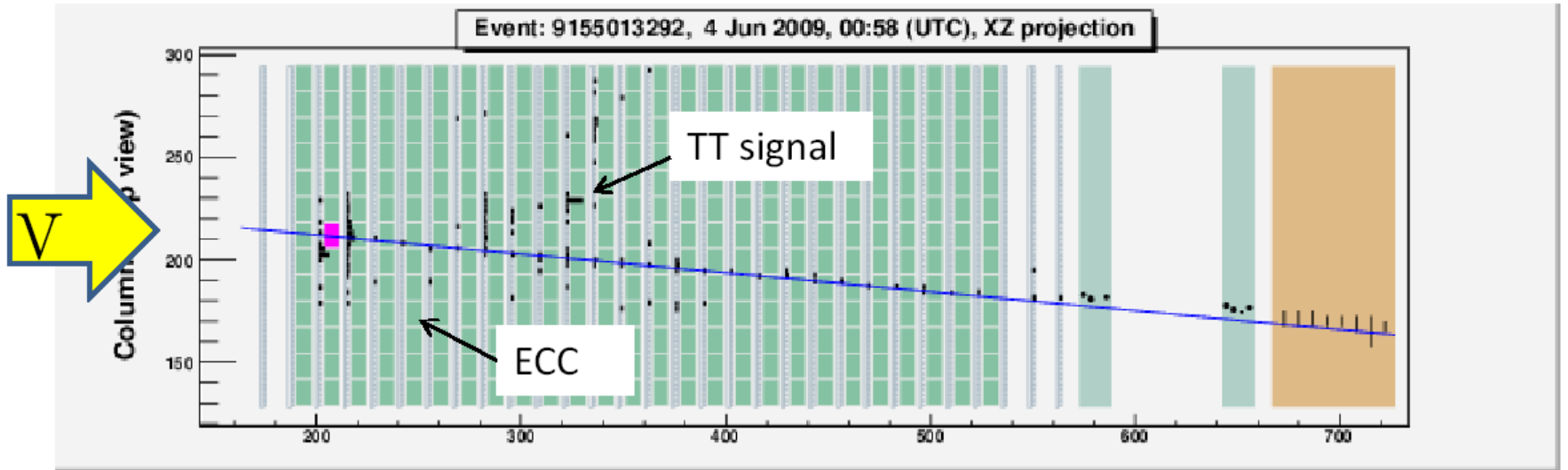


**56 Lead Plates + 57 Films**

**~ structure same as DONUT ECC**



# Target Tracker による Brick ID



平均的なスキャン面積

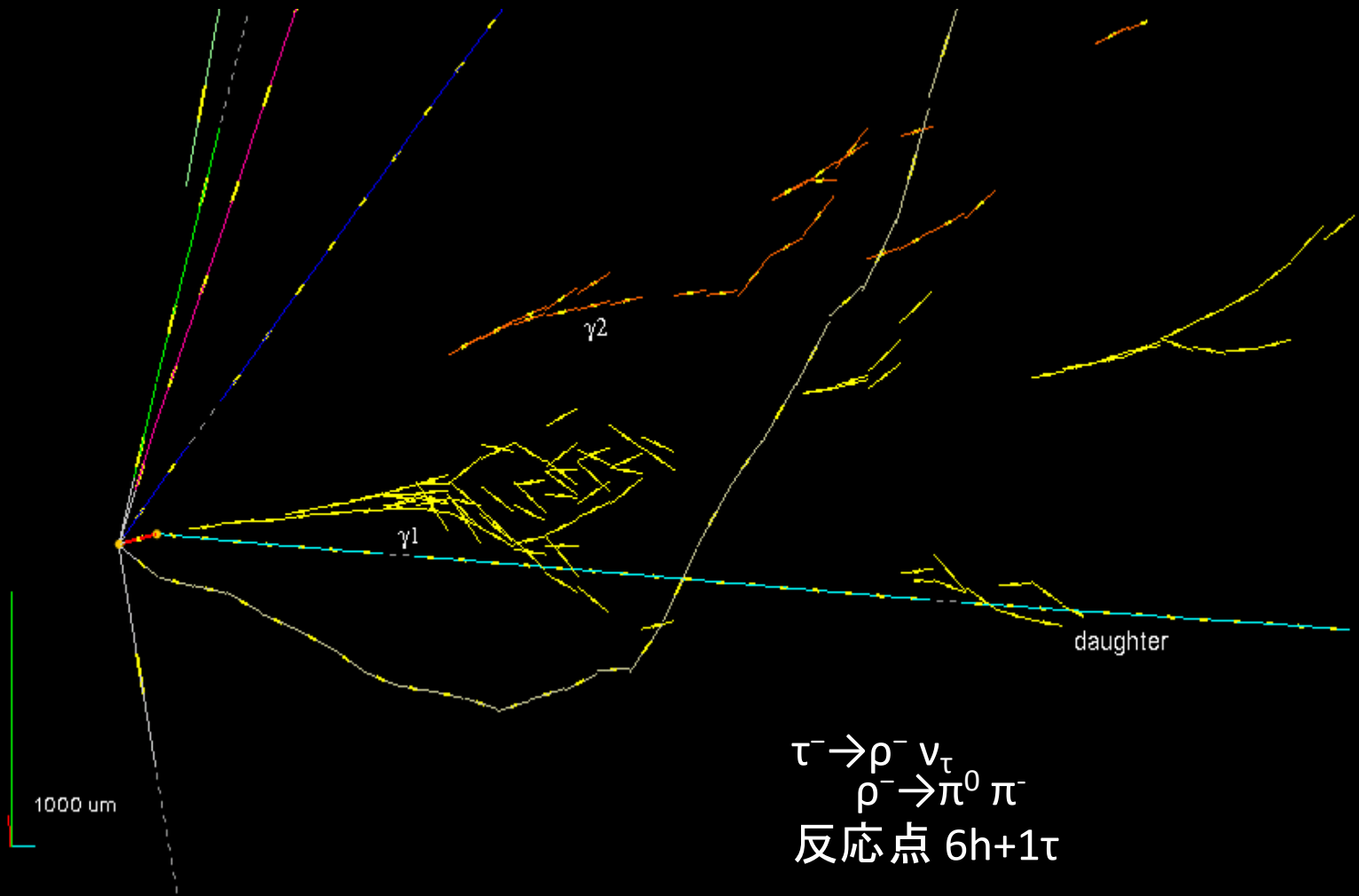
CC like : 26 cm<sup>2</sup>

NC like : 61 cm<sup>2</sup>

max.30ev/day

# 1<sup>st</sup> $\nu_\mu \rightarrow \nu_\tau$ event in OPERA

2010



# Significance

Decay channel	Expected signal	Observed	Expected background			
			Total	Charm decays	Hadronic re-interactions	Large-angle muon scattering
$\tau \rightarrow 1h$	$0.41 \pm 0.08$	2	$0.033 \pm 0.006$	$0.015 \pm 0.003$	$0.018 \pm 0.005$	–
$\tau \rightarrow 3h$	$0.57 \pm 0.11$	1	$0.155 \pm 0.030$	$0.152 \pm 0.030$	$0.002 \pm 0.001$	–
$\tau \rightarrow \mu$	$0.52 \pm 0.10$	1	$0.018 \pm 0.007$	$0.003 \pm 0.001$	–	$0.014 \pm 0.007$
$\tau \rightarrow e$	$0.62 \pm 0.12$	0	$0.027 \pm 0.005$	$0.027 \pm 0.005$	–	–
Total	$2.11 \pm 0.42$	4	$0.233 \pm 0.041$	$0.198 \pm 0.040$	$0.021 \pm 0.006$	$0.014 \pm 0.007$

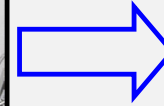
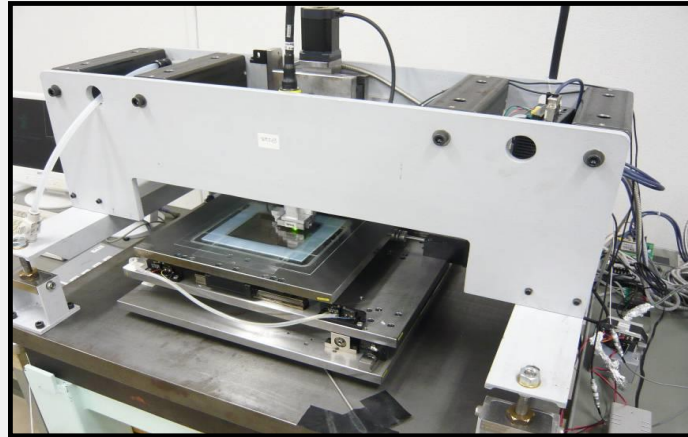
p-value =  $1.24 \times 10^{-5}$

4.2 $\sigma$  Significance for the existence of  $\nu_\mu \rightarrow \nu_\tau$

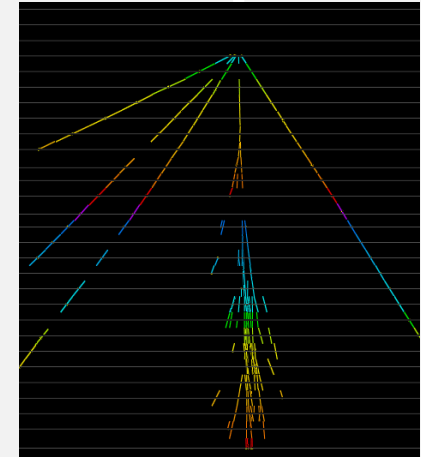
$\Delta m^2_{23}$  3.1 [ 1.8, 5.0]  $\times 10^{-3}$  eV<sup>2</sup> Assuming  $\sin 2\theta_{23}=1$



# Launching Nuclear Emulsion into various field



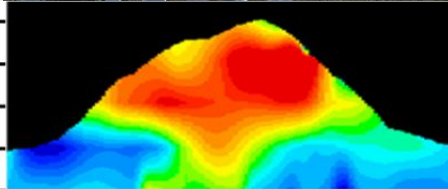
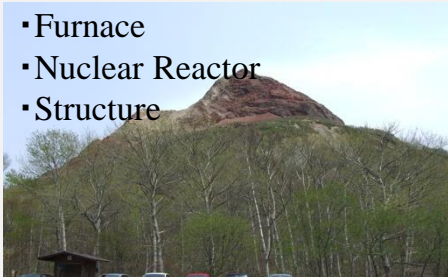
## High Energy Physics Neutrino oscillation (OPERA)



## Applied physics

### Muon-radiography

- Volcano
- Furnace
- Nuclear Reactor
- Structure



東大地震研究所と共同研究 936

### Neutron

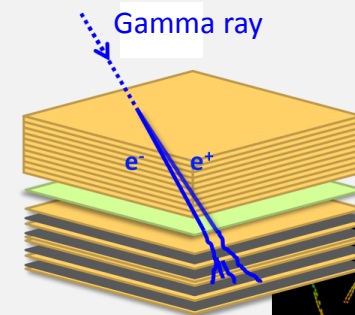
(Direction, Energy)

- Nuclear Fusion
- Imaging
- Dosimeters
- Dark-matter



### Astrophysics

Gamma ray telescope (GRAINE)



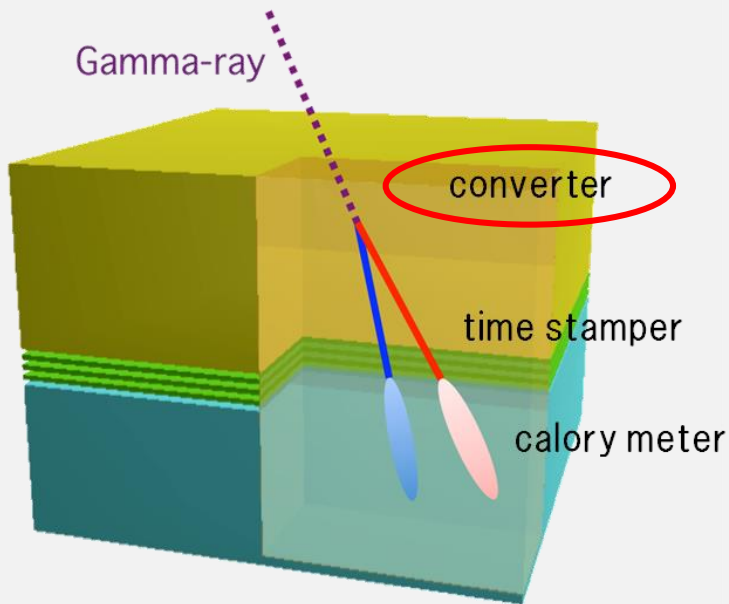
Developing next generation system  
with the speed of  $\sim 1\text{m}^2/\text{h}$  : HyperTS

# GRAINE Gamma-Ray Astro-Imager with Nuclear Emulsion

Nagoya, Kobe, JAXA/ISAS, Aichi Edu. , Okayama Science, Utsunomiya

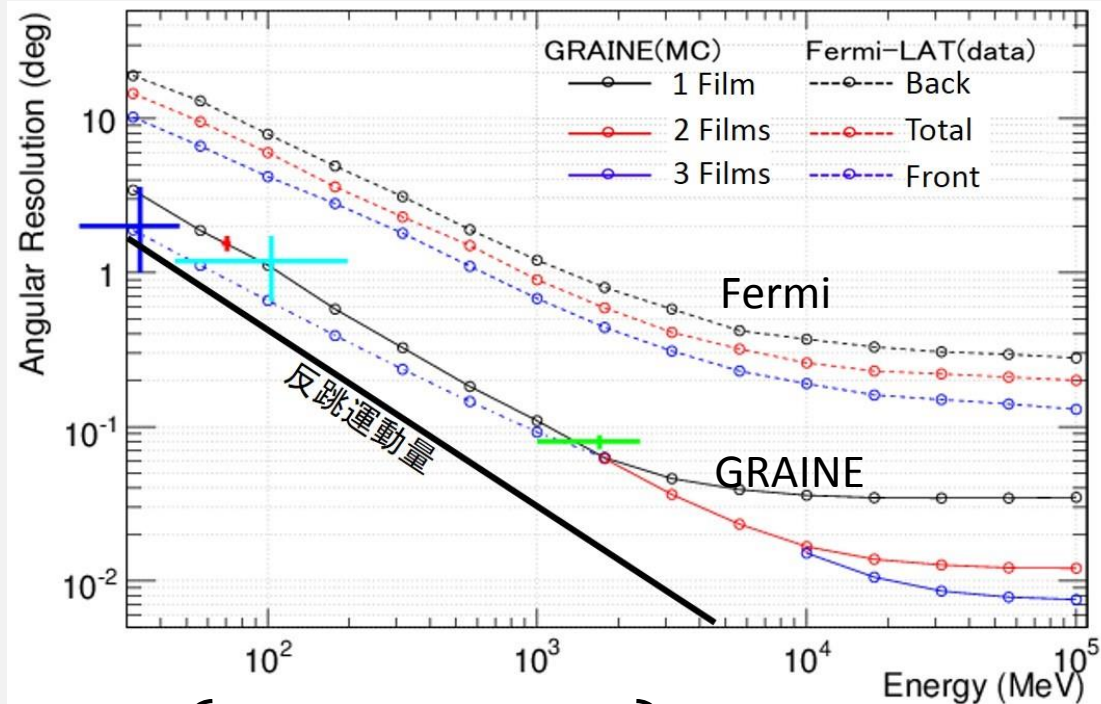
Target : 10MeV—100GeV  $\gamma$ -ray Balloon exp.

Emulsion  $\gamma$  ray telescope



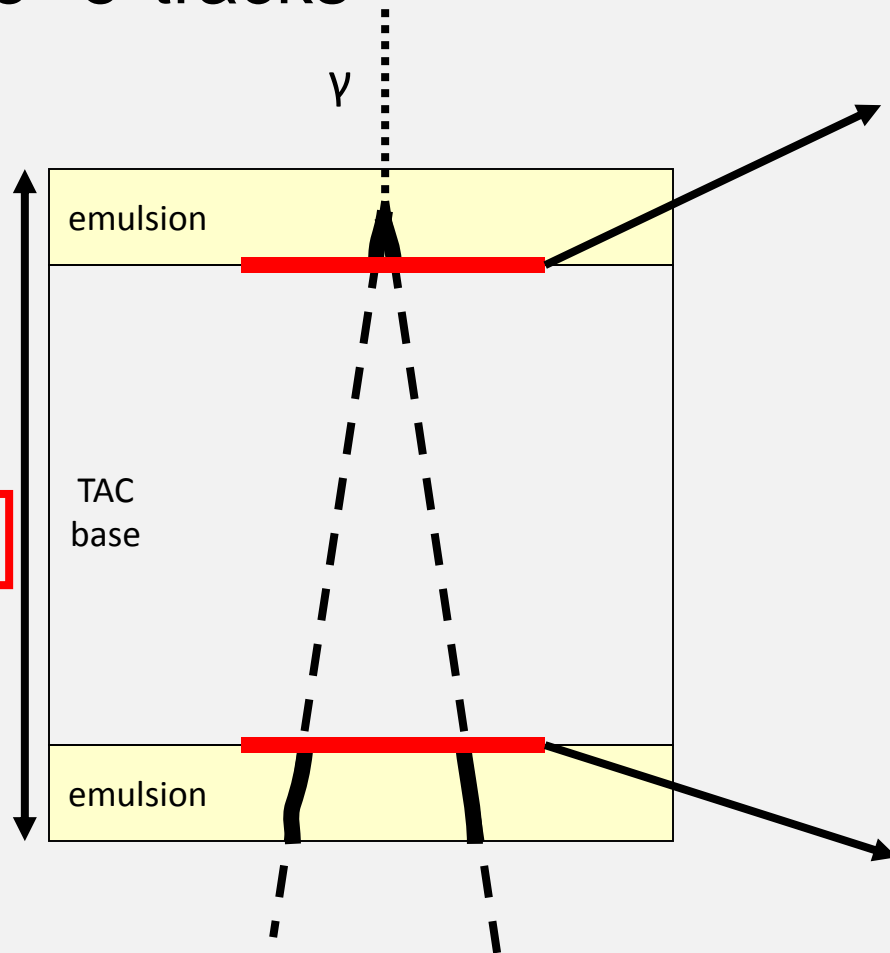
The incident direction of the Converted electron pairs by Emulsion

Angular Resolution of Emulsion telescope

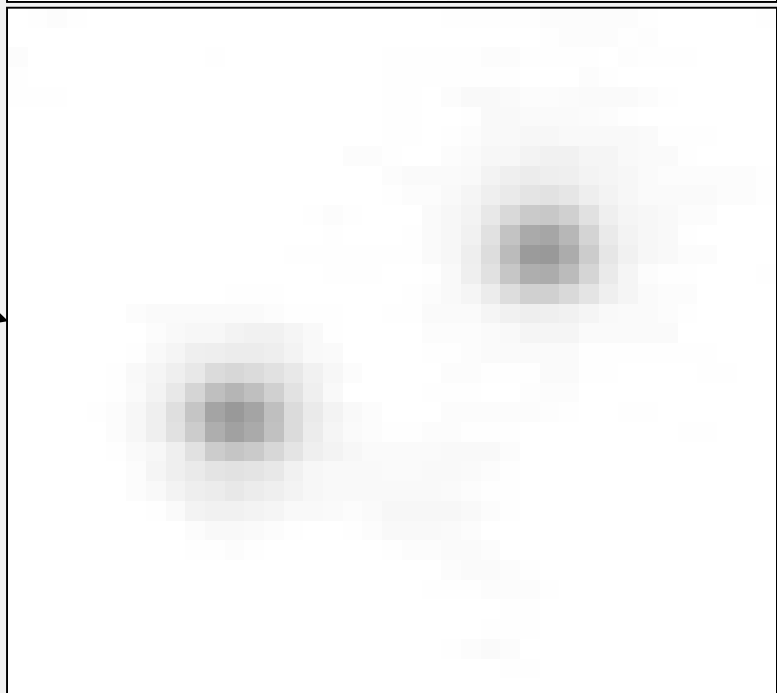
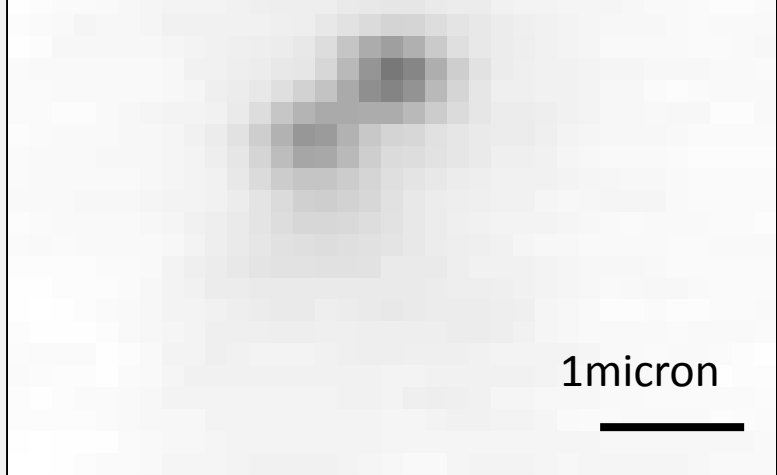


$\left[ \begin{array}{l} 10 \text{ mrad @ } 100 \text{ MeV} \\ 1.5 \text{ mrad @ } 1 \text{ GeV} \end{array} \right]$

# Precise measurement of the $e^+ e^-$ tracks



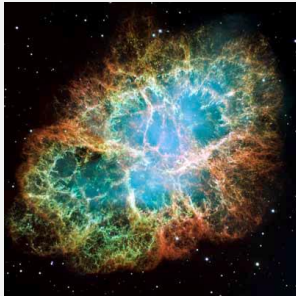
## Microscopic view of a pair creation



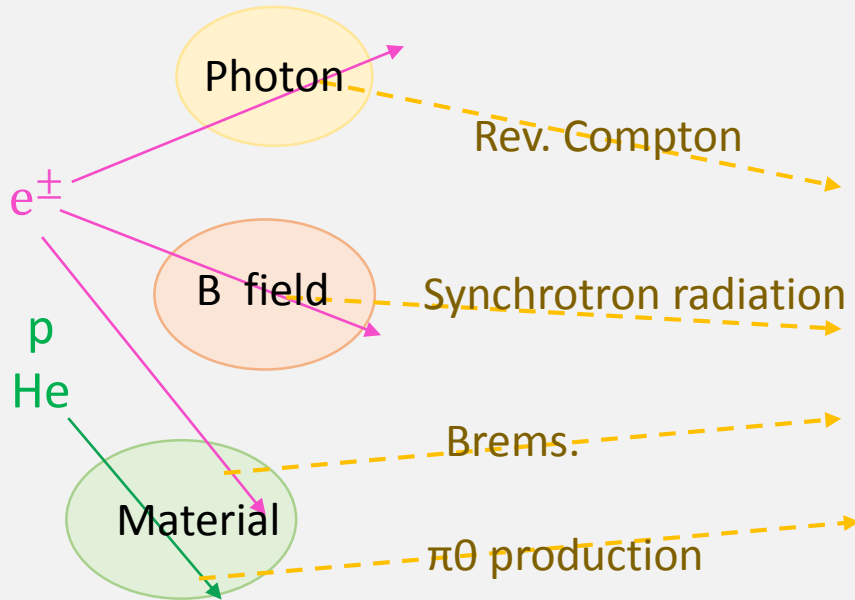
# γ Ray Astronomy

- SuperNova
- Pulsar (Neutron Star)
- Active Galactic Nuclei (Black Hole)
- Transit events GRB, flare ...

かに星雲、かにパルサー



NASA HUBBLE



Satellite

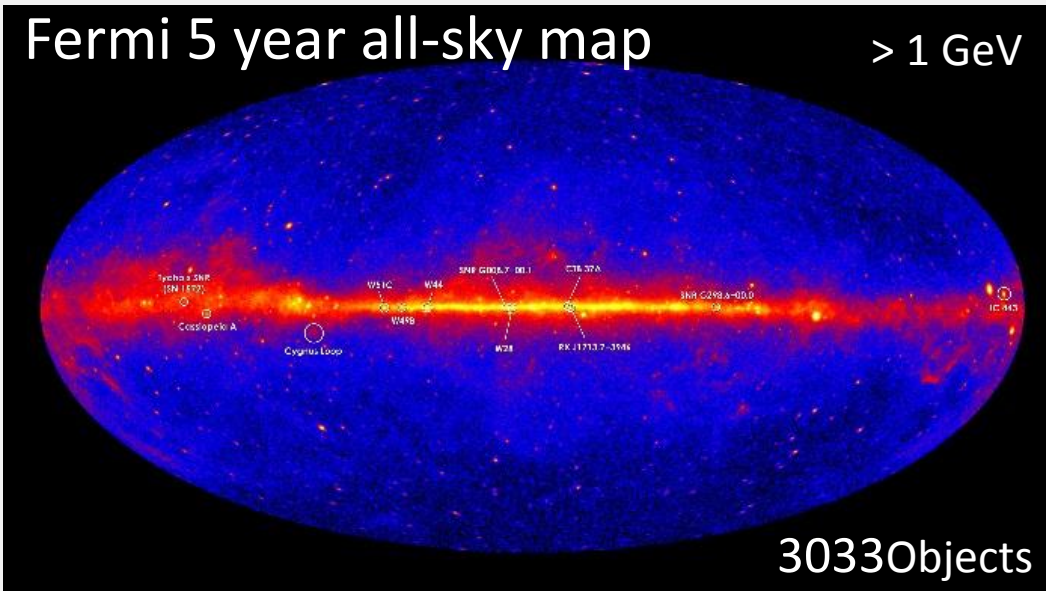


Balloon JAXA

## Fermi-LAT の観測

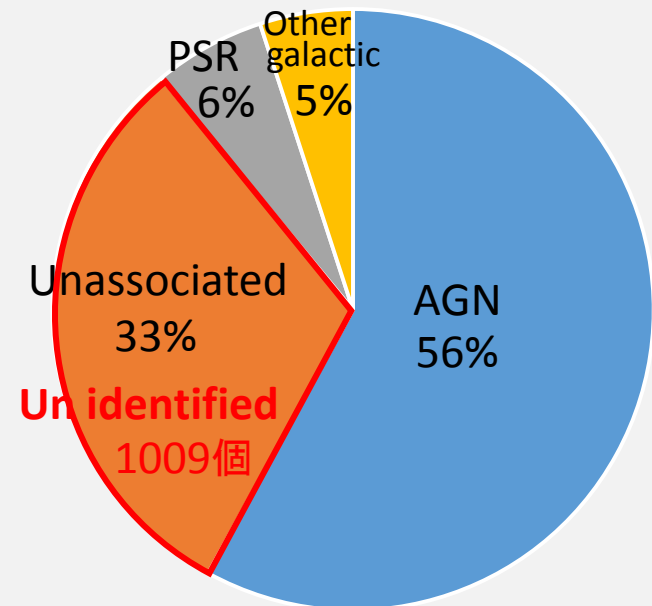
### Fermi 5 year all-sky map

> 1 GeV



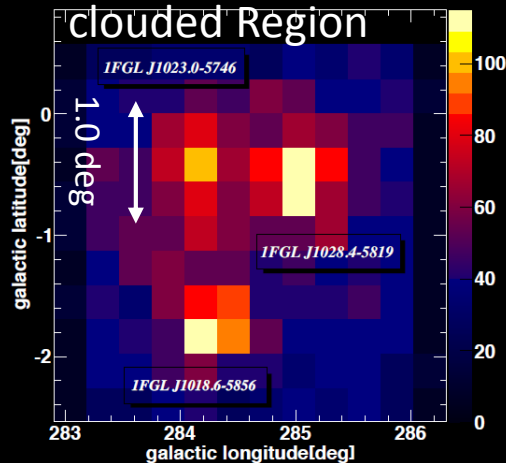
3033 Objects

### Contents of 3033



# Fermi-LAT (data)

## Observation of clouded Region



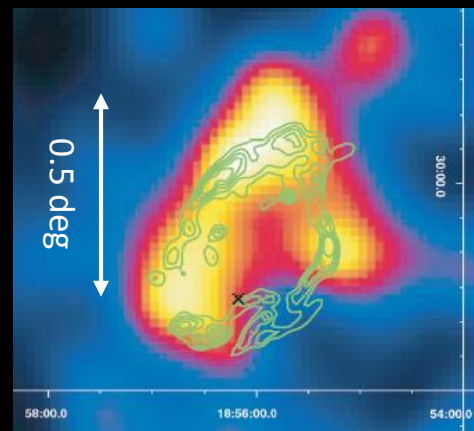
Energy  
1–3 GeV

Observation  
~ 6 month

1FGL J1018.6-5856  
1FGL J1023.0-5746  
1FGL J1028.4-5819

From Fermi Science  
Support Center  
Fermi 1<sup>st</sup> catalog

## Super Nova Remnant



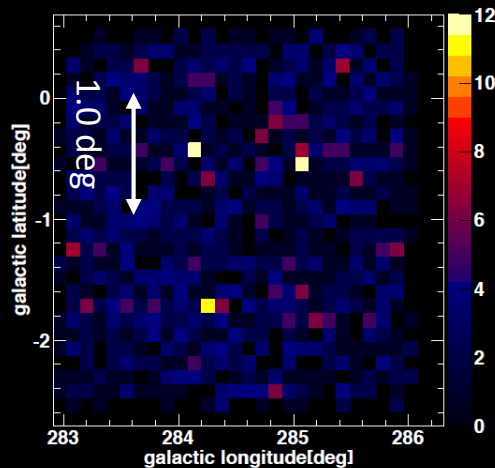
Energy  
2–10 GeV

Observation  
~ 6 month

SNR W44

A. A. Abdo. et al.  
(2010) Science

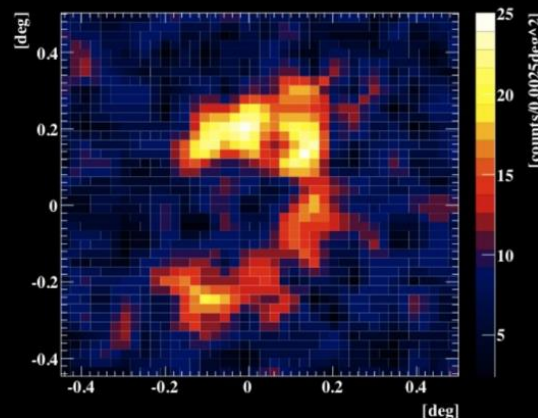
# GRAINE (MC)



Energy  
1–3 GeV

Observation  
~150 m<sup>2</sup>·hour  
for 5 $\sigma$  detection

## SNR W44

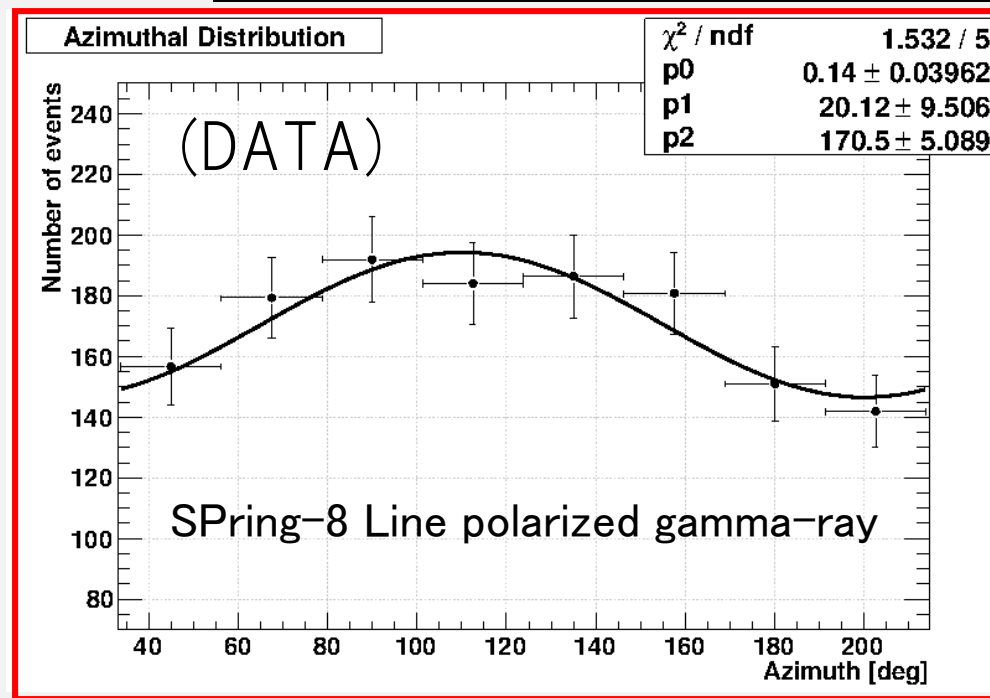
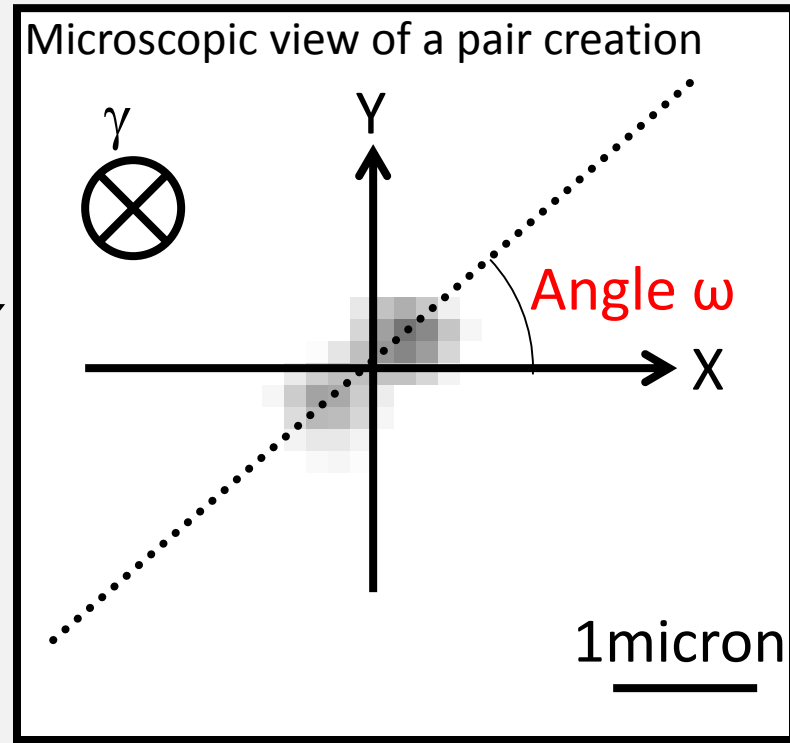
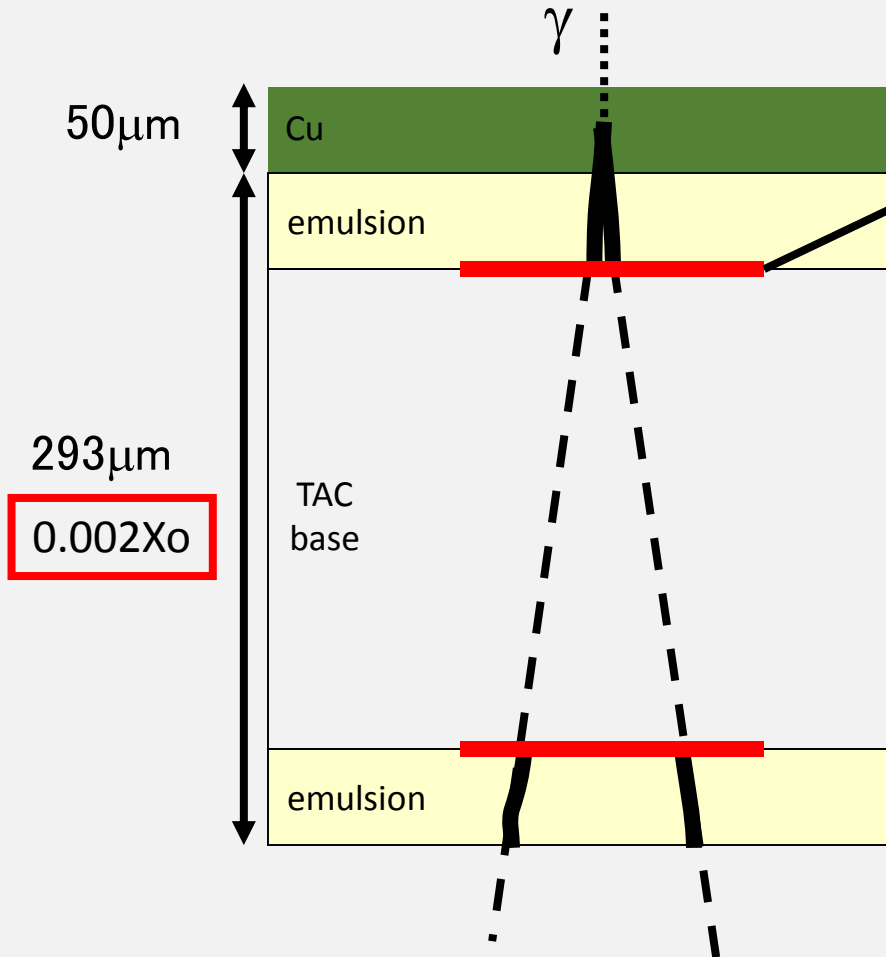


Energy  
> 1 GeV

Observation  
1000 m<sup>2</sup>·hour

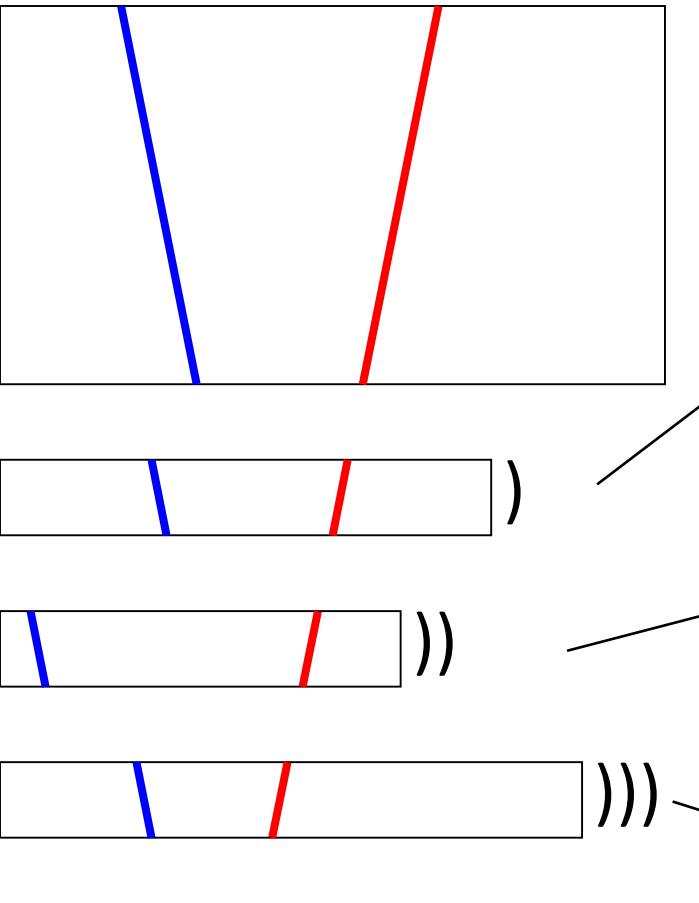
Need to realize large aperture + long flight  
Aiming 10m<sup>2</sup>/Flight + 1 Weeks/Flight

# Polarity Measurement

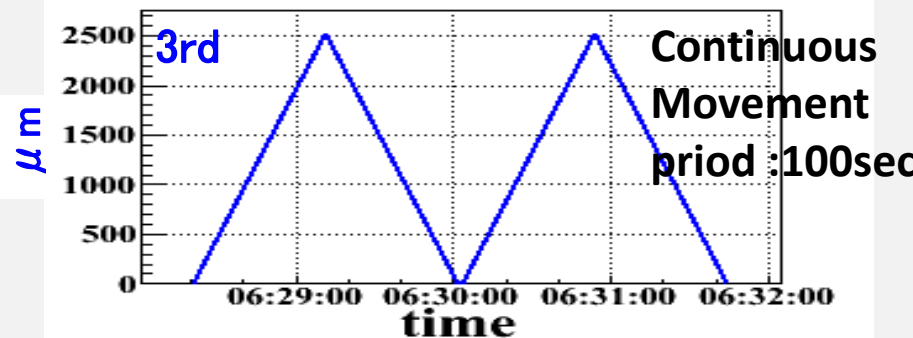
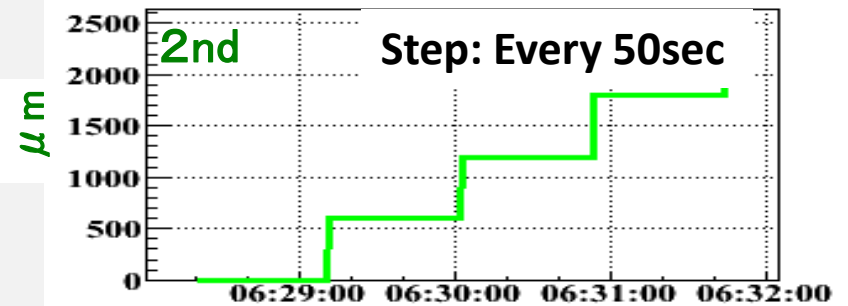
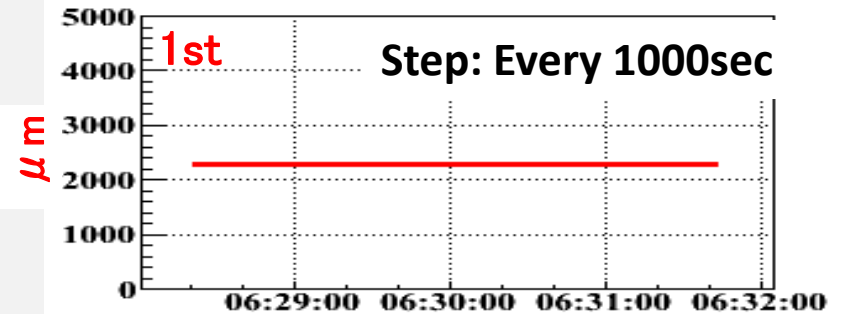


**GRAINE can measure the Polarity  
(Proven by  $3.5\sigma$ )  
Fermi : impossible**

# Time Stamp System = Shifter



Aim to resolve **10**msec



A scanning speed of  $1000\text{m}^2$  /year or more is required.

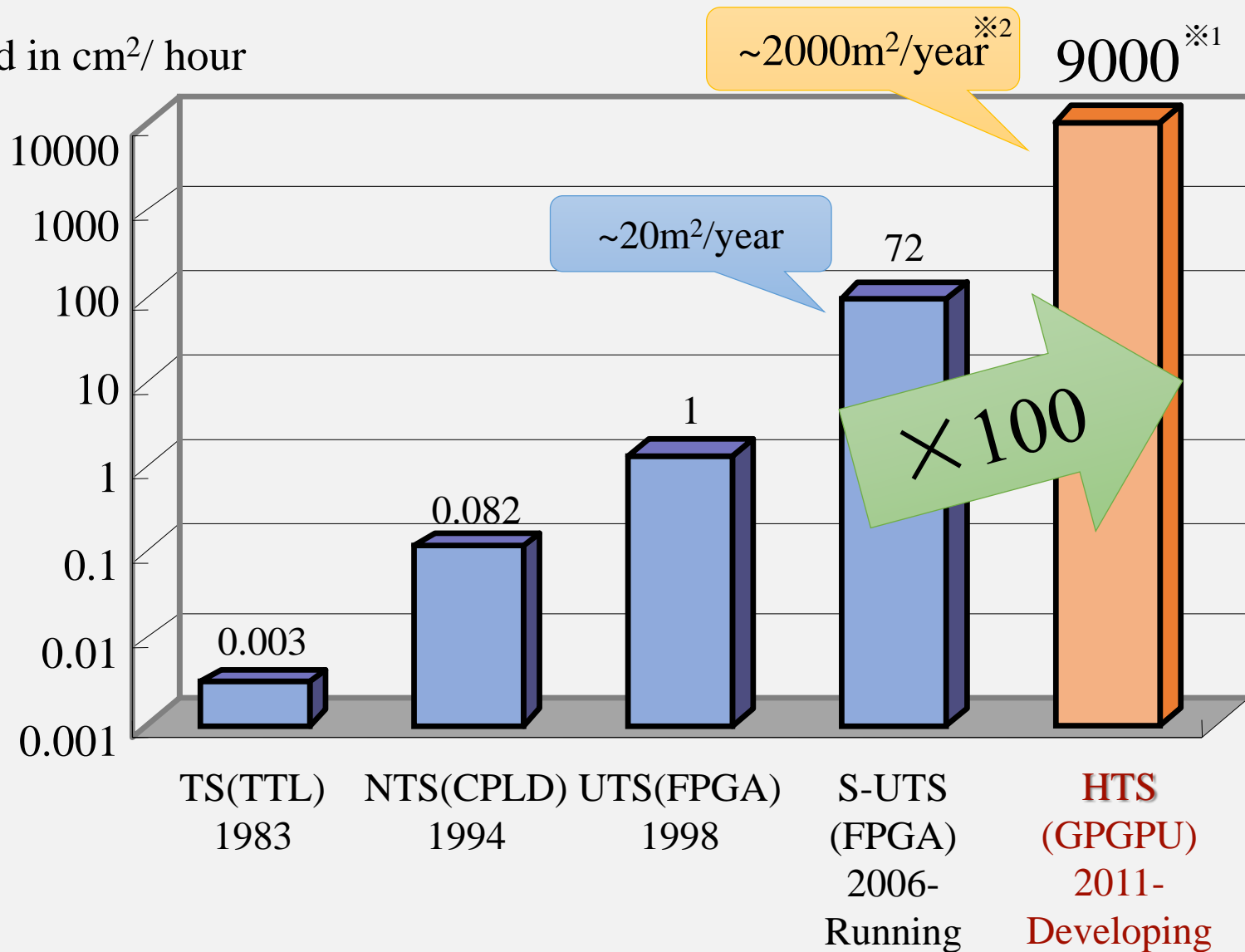
Two orders of magnitude faster.



# Evolution of the Scanning Speed

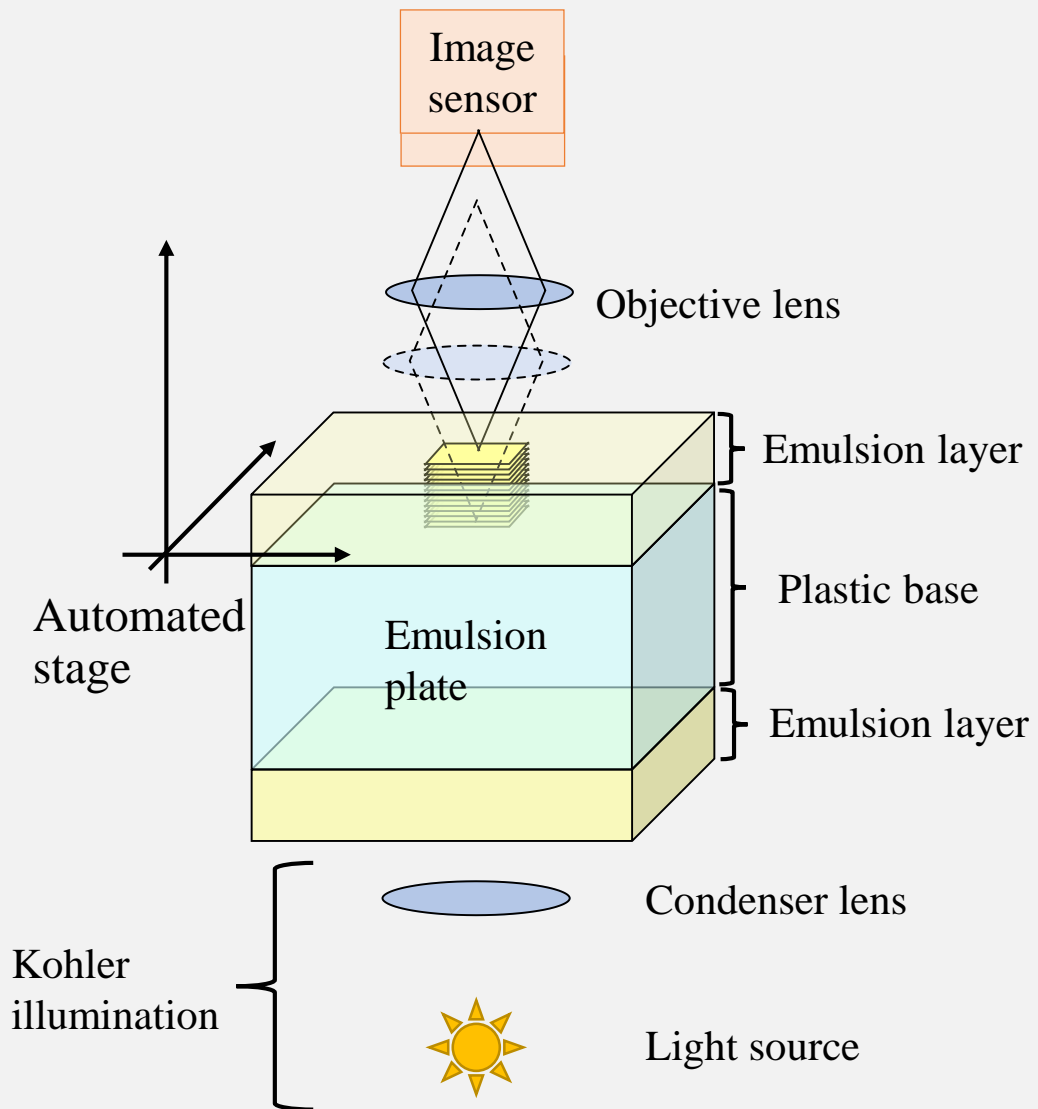
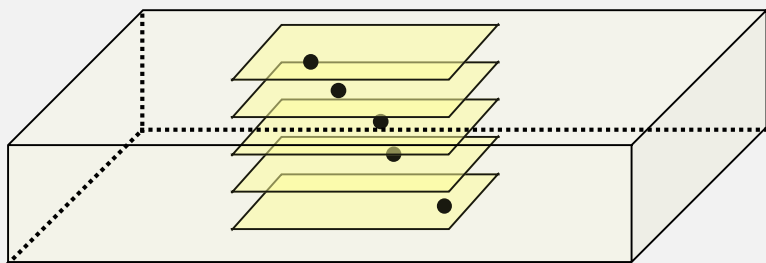
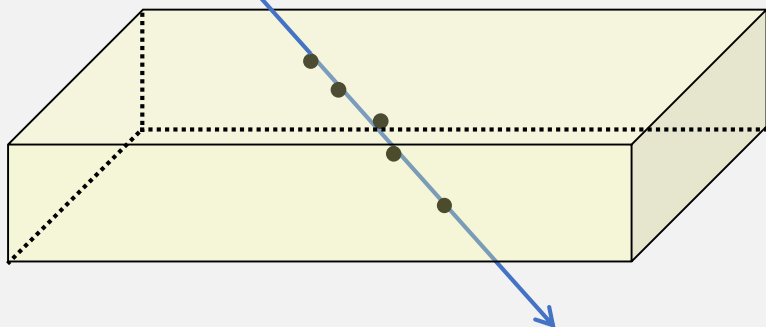
※1 Area of each layer  
 ※2 Area of the films

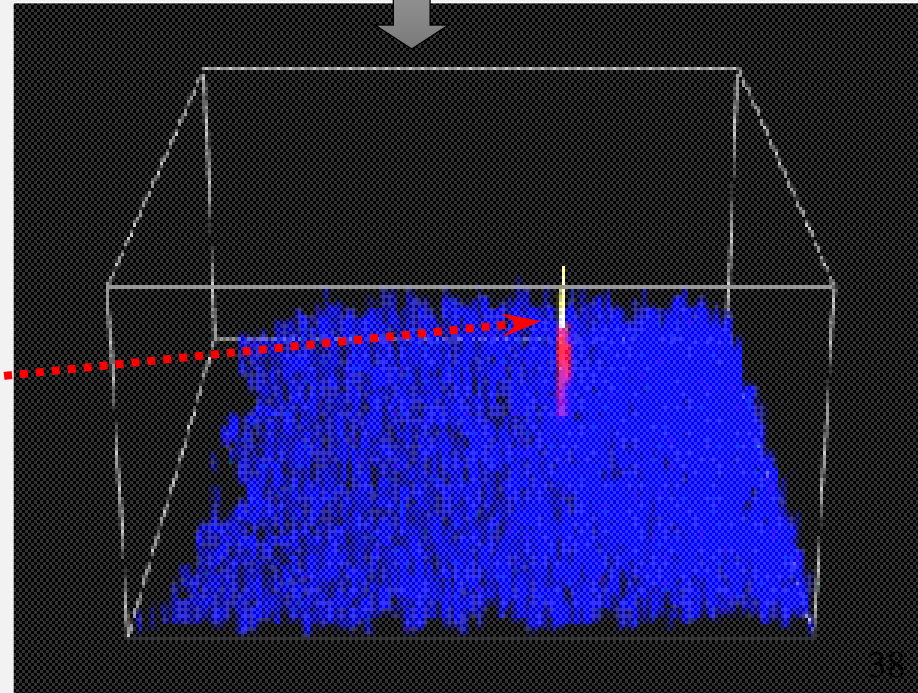
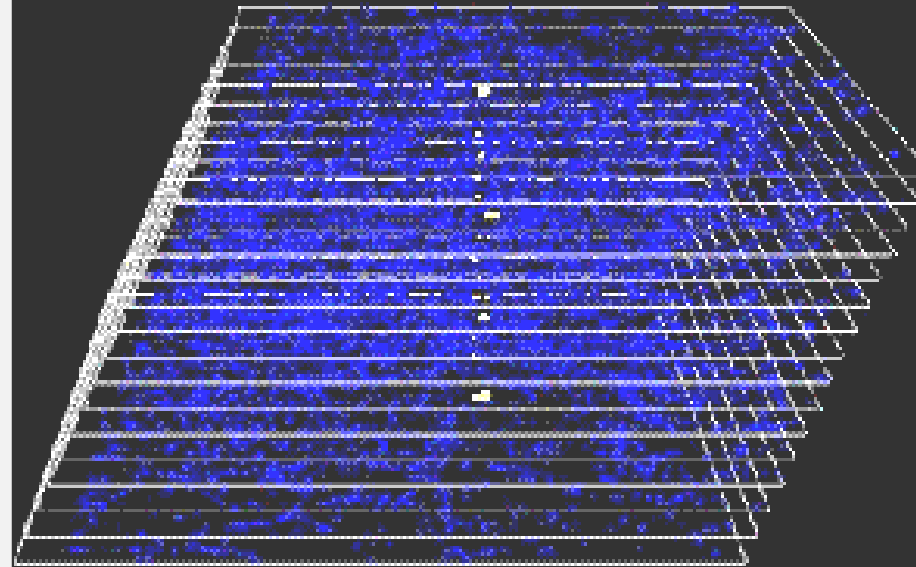
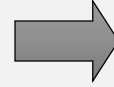
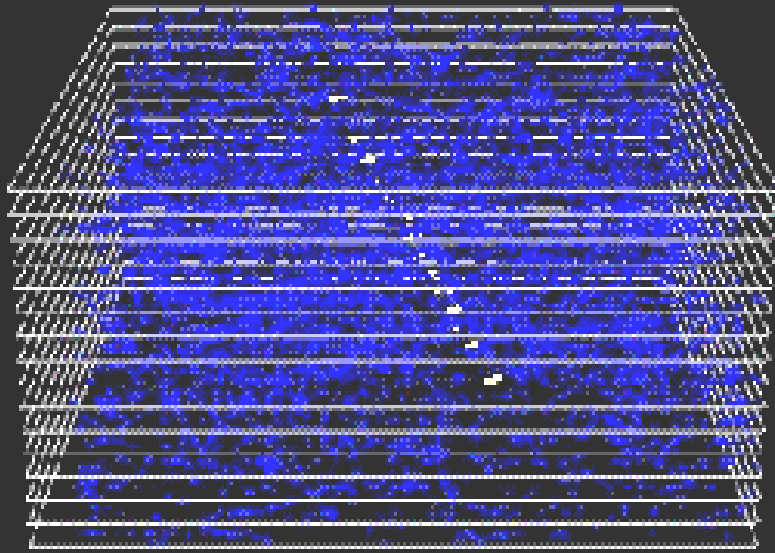
Speed in cm<sup>2</sup>/ hour



# Digitizing Nuclear Emulsion

Charged particles



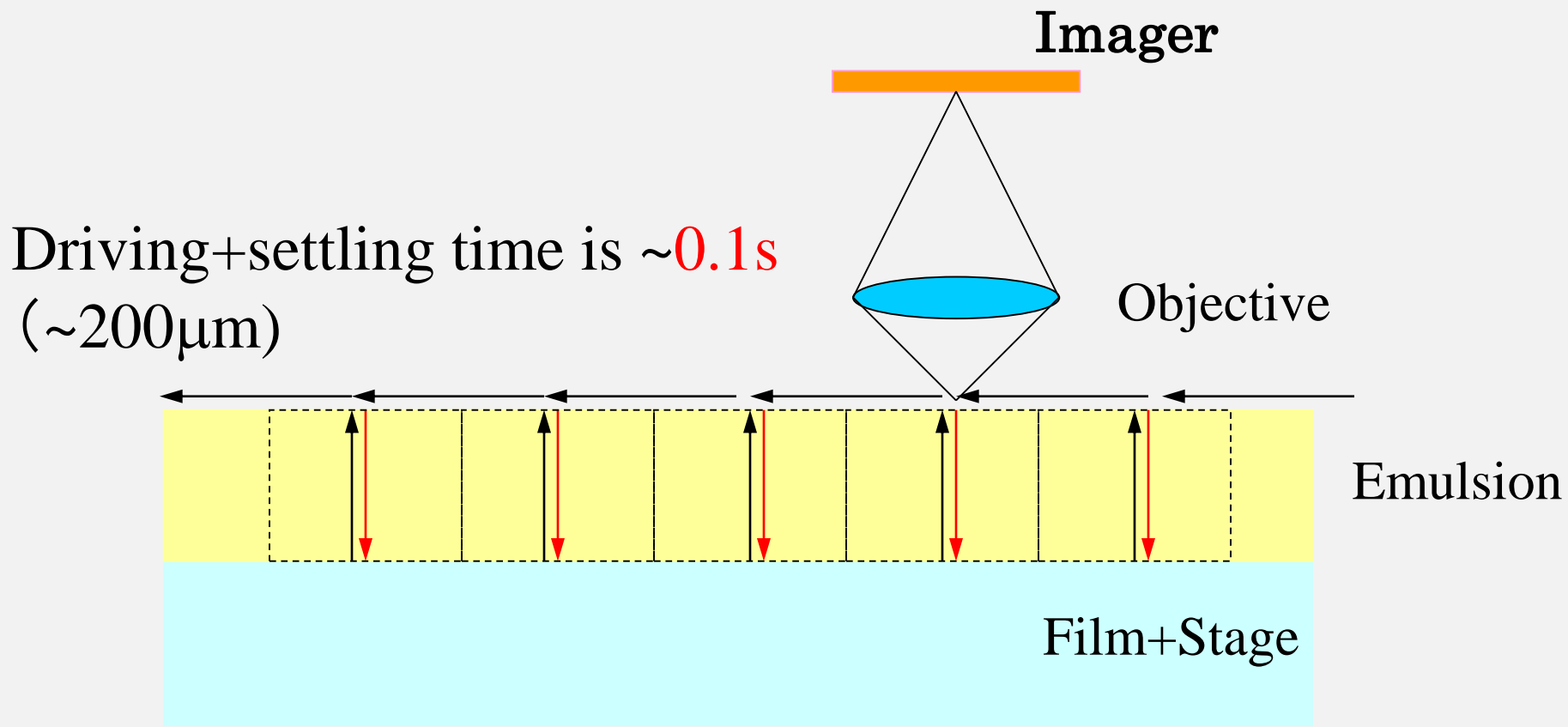


## Track recognition method

- Take 16 tomographic images by microscope optics.
- Shift images to aim at specific angle tracks.
- Sum up 16 images to examine coincidence.
- Find signal of tracks.
- Repeat for all angles in space, >2000 times

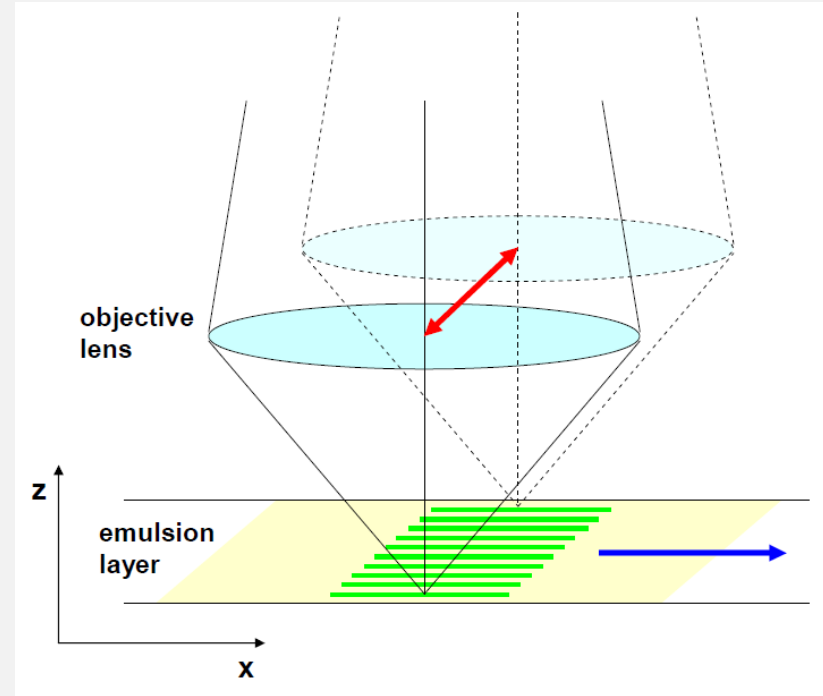
*Invented by K. Niwa in 1974*

# Mechanics is also the bottleneck



# The features of the previous system “SUTS”

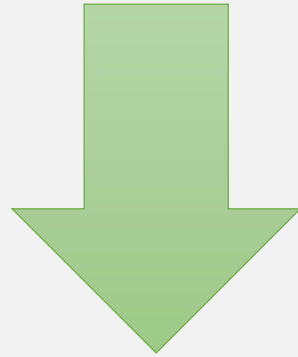
- Ultra High Speed Camera
  - Up to 3k frames per second.
  - 60 view/sec (20times)
- Image taking by follow shot
  - No step and repeat operation can avoid a mechanical bottleneck.
  - High speed motion of the objective lens can be done by piezo actuators
- Optimizing Field of View
  - 120mm × 90mm -> 200mm × 200mm (4 times area)
- FPGA for image processing



Maximum scanning speed is 72cm<sup>2</sup>/h

# Concept of HTS (Hyper Track Selector)

- It is difficult to drive objective much more quickly.



- Field of view can be a few orders of magnitude larger.



**Parallel Processors  
72 GPU + 36 CPU**

**Wide View Lens**

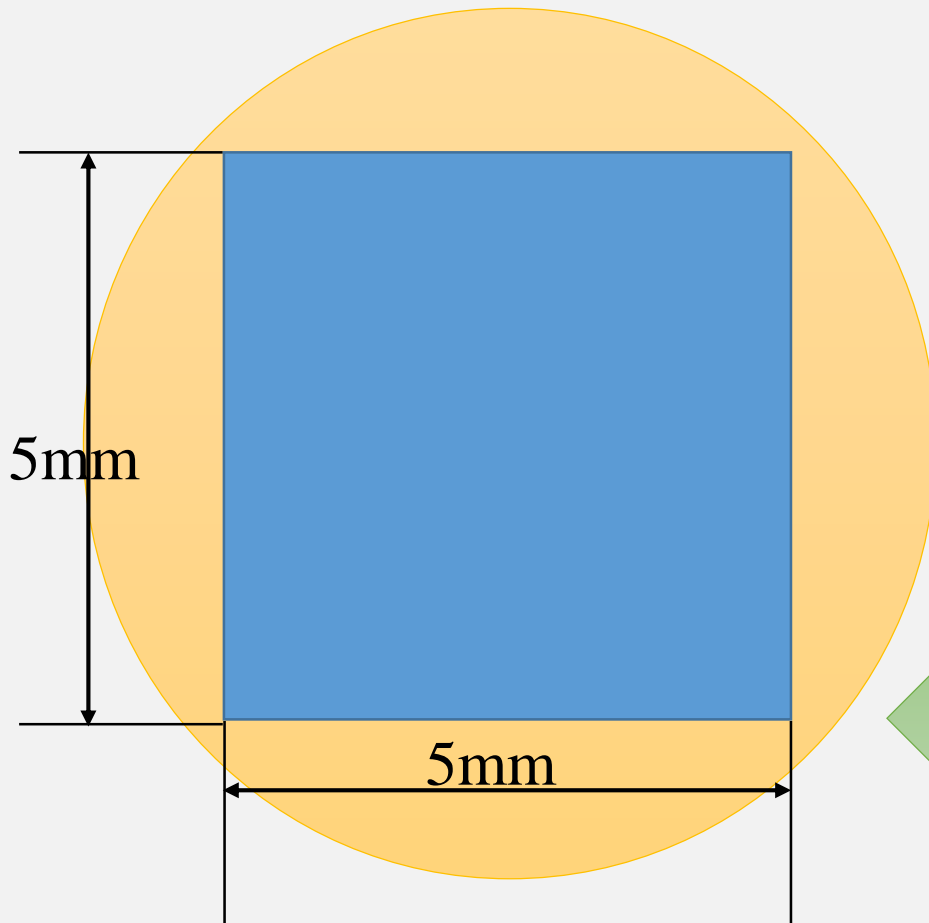
**72ch Camera  
2M pixel/Camera**

**High Precision  
X-Y-Z Stage**

**New Read-out system HTS  
( Hyper Track Selector )**

# Wide field of view

Field of view (FOV) of HTS



← × 600

S-UTS

■  
~0.2mm





# Big Objective Lens

Resolution : ~420nm

N.A. : 0.65

Light source : g-line (436nm)

Magnitude :  $\times 12.2$

**F.O.V : 5.1 (H)  $\times$  5.1 (V)mm**

#of image plane 6

(by Beam splitter)

Weight : 80kg



# Resolution : “Numerical Aperture”

- Spatial resolution :

$$R_{res} = 0.61 \cdot \lambda / NA$$

NA=0.65,  $\lambda=436\text{nm}$  :  $0.40\mu\text{m}$  HTS

NA=0.85,  $\lambda=550\text{nm}$  :  $0.39\mu\text{m}$  SUTS

**No significant difference**

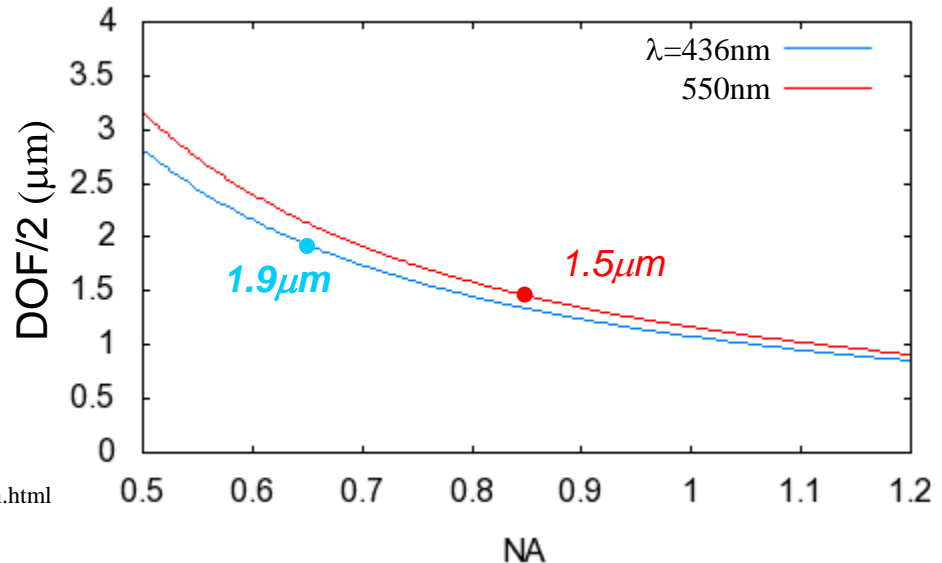
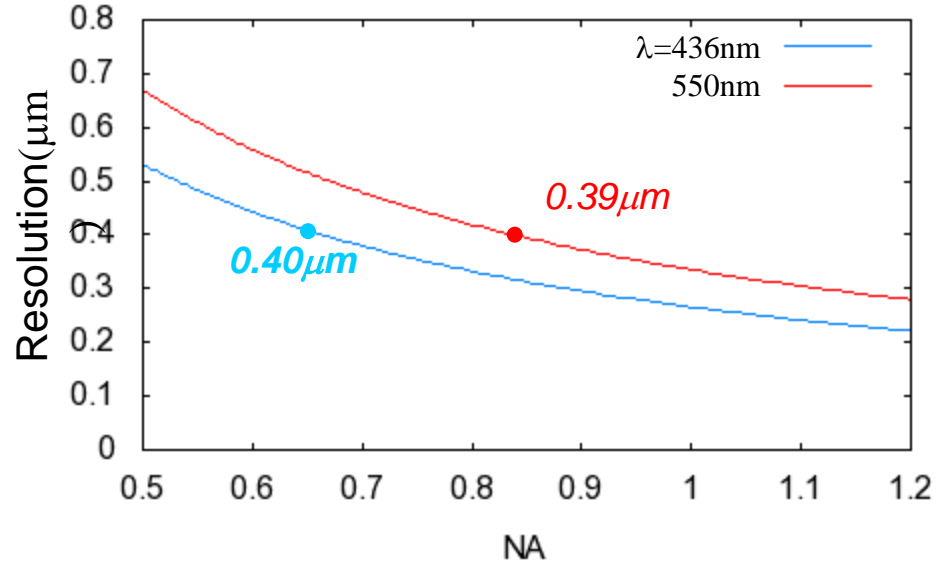
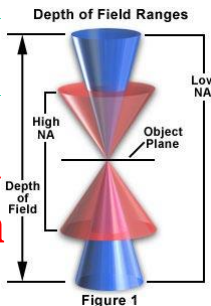
- Depth of field :

$$DOF = \underbrace{1.0 \cdot n / NA}_{\text{Circle of confusion}} + \underbrace{n \cdot \lambda / NA^2}_{\text{(Modified BERKEK formula)}}$$

NA=0.65,  $\lambda=436\text{nm}$  :  $\pm 1.9\mu\text{m}$

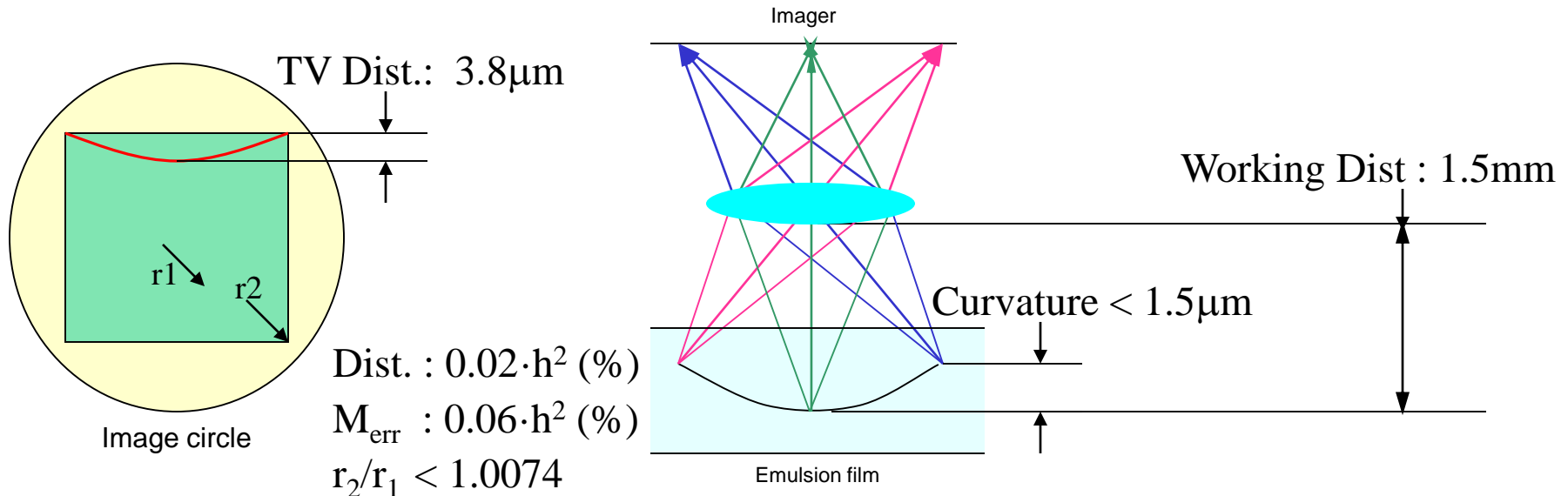
NA=0.85,  $\lambda=550\text{nm}$  :  $\pm 1.5\mu\text{m}$

**27% worse, however emulsion thickness can be adjusted even after developing.**



# Distortion (Optical aberration)

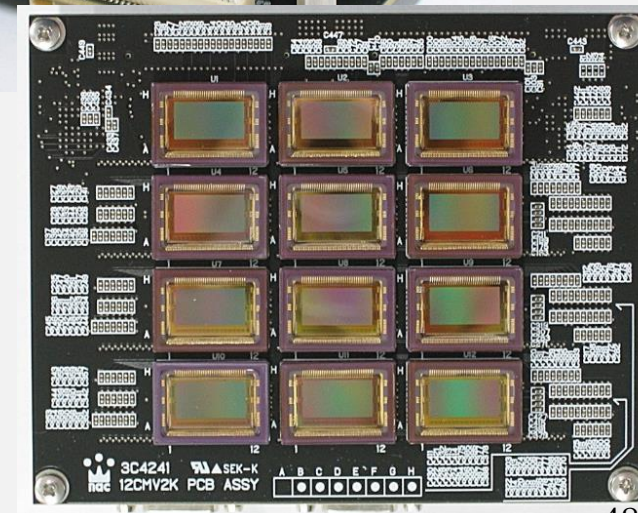
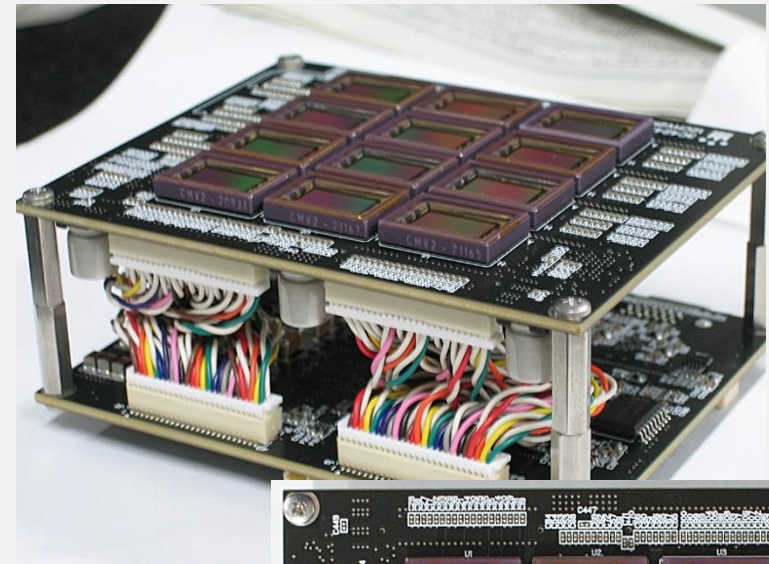
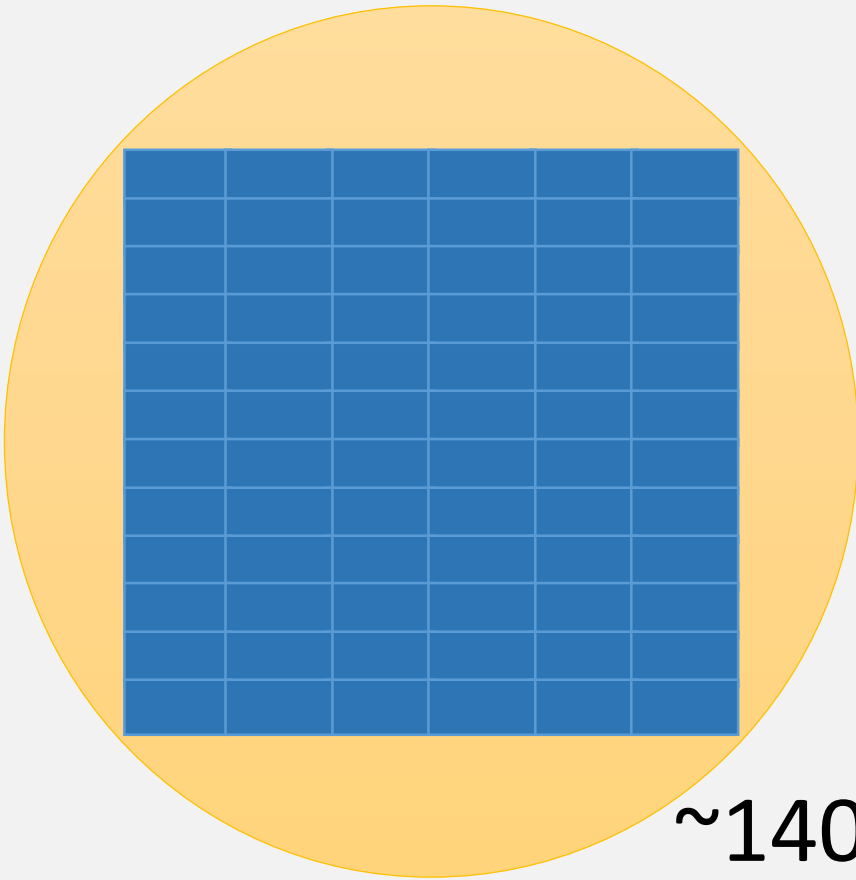
TV distortion :	0.075%	-> linearity <math> < 4\mu\text{m}/5\text{mm}</math>
Distortion :	0.25% max.	-> ~0.74% Magnification Error
Field curvature :	<math> < 1.5\mu\text{m}</math>	-> No loss frame
Working distance:	1.5mm	-> Accept thick emulsion film



# Speed and Coverage of Mosaic Imager

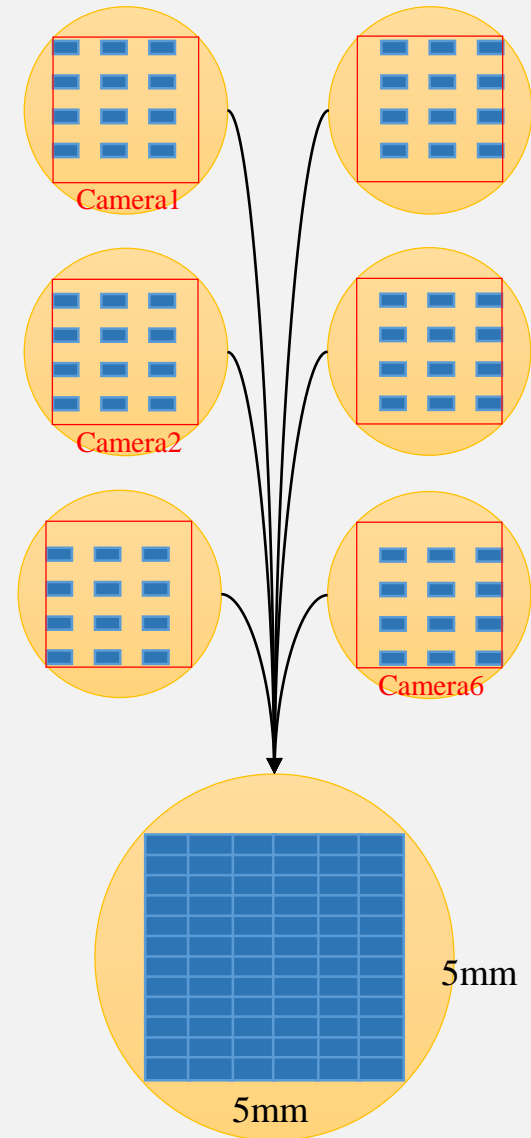
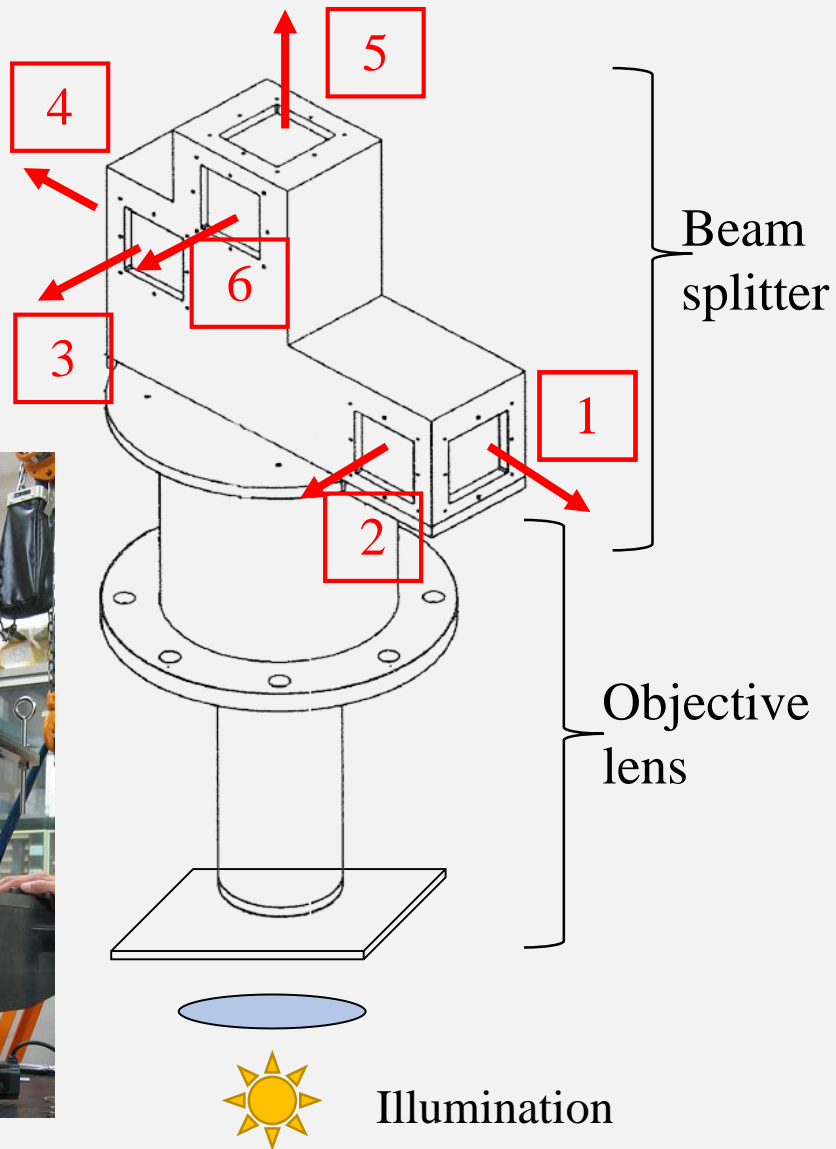
Divide FOV into 72 parts.  
Need the sensor of 2M pixel and 340fps.

Specially developed Mosaic Imager



~140M Pixels

# Mosaic Imager system



# How high throughput can be achieved

Throughput = area of FOV  $\times$  Repetition rate.

FOV : 600 times larger

To achieve 100 times faster than S-UTS,

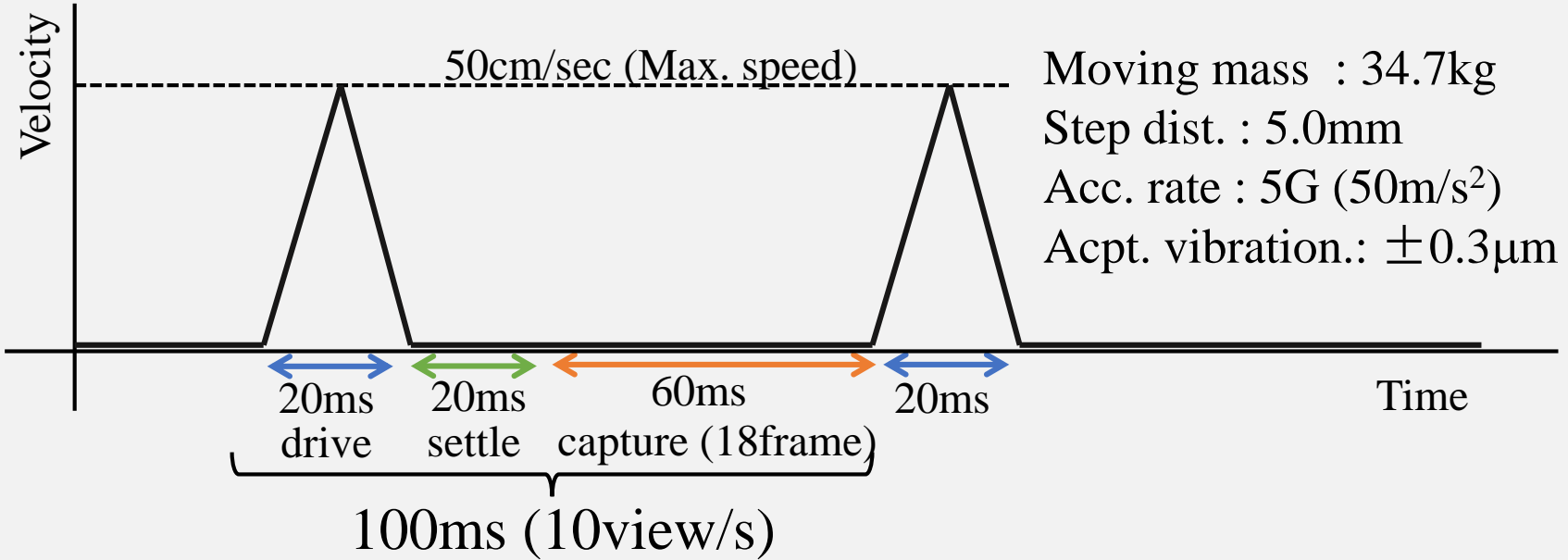
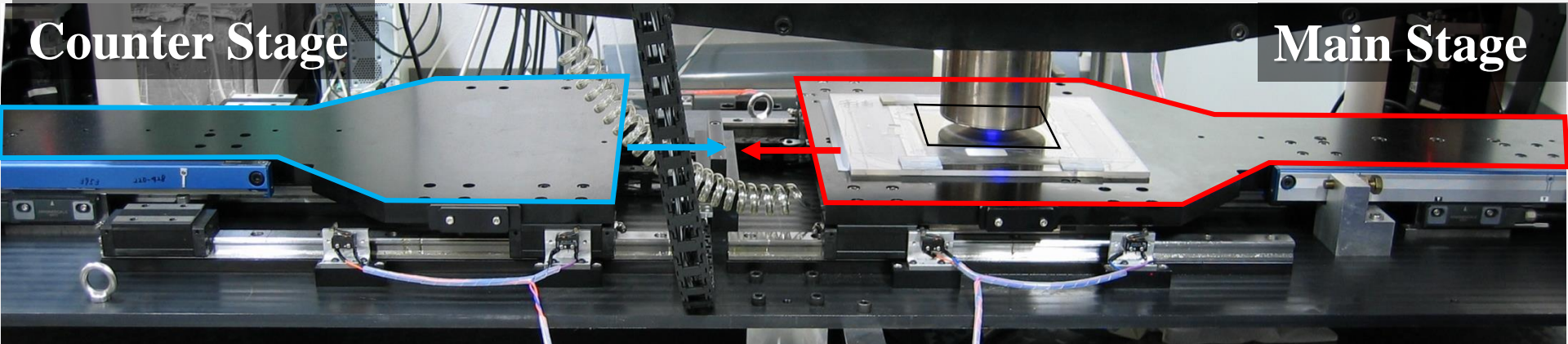
Repetition rate should be  $>10$ view/s (1/5 of SUTS)

It takes 60ms to take images at least.

- HTS takes advantage of Stop & Go in image capturing.
- Stopping accuracy should be  $0.3\mu\text{m}$ .
- The key is how to stop quickly and precisely.

# High precision and speed stage

Design value

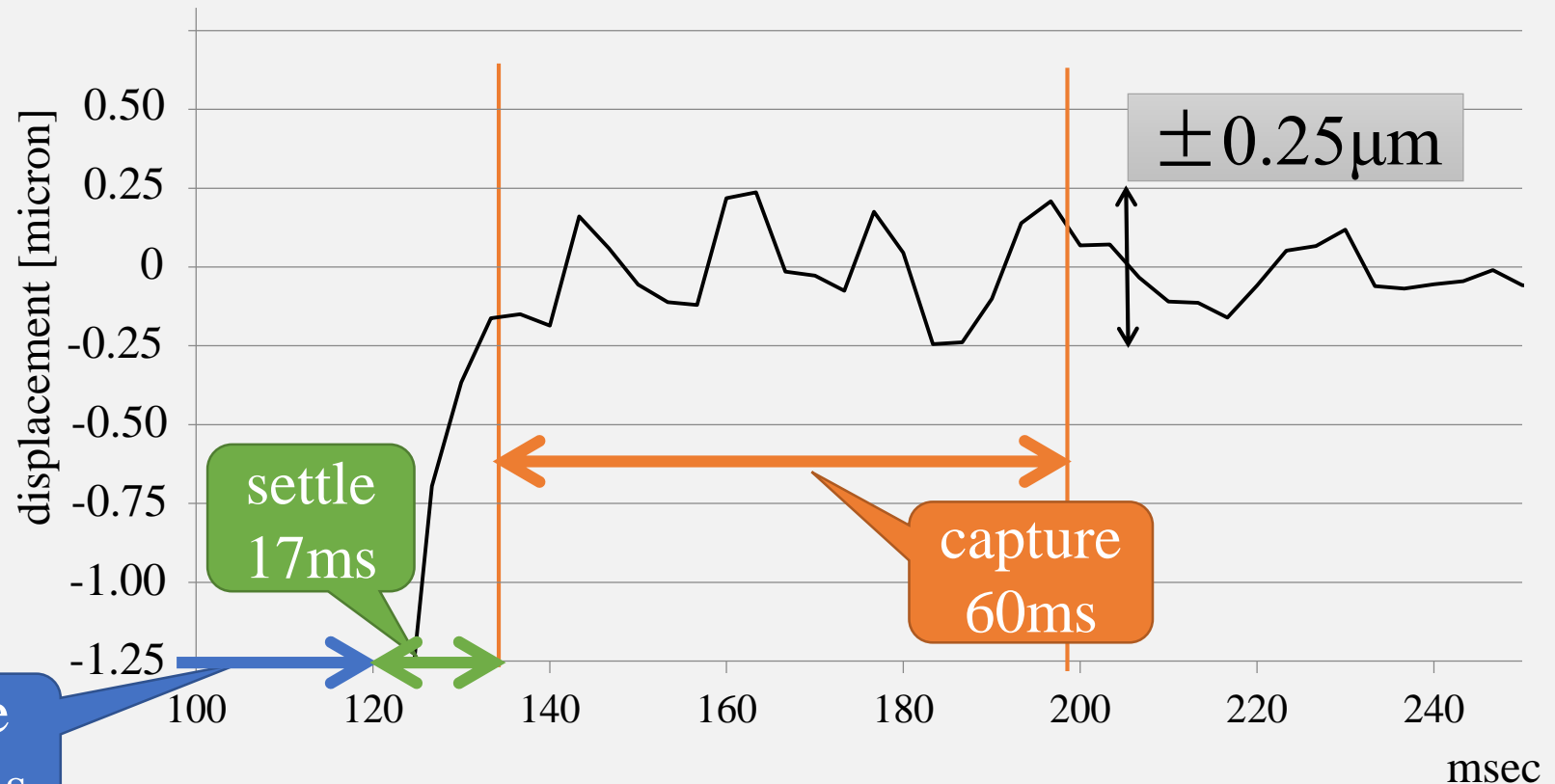


Reaction force is canceled by counter stage

# Evaluation of stage settling time

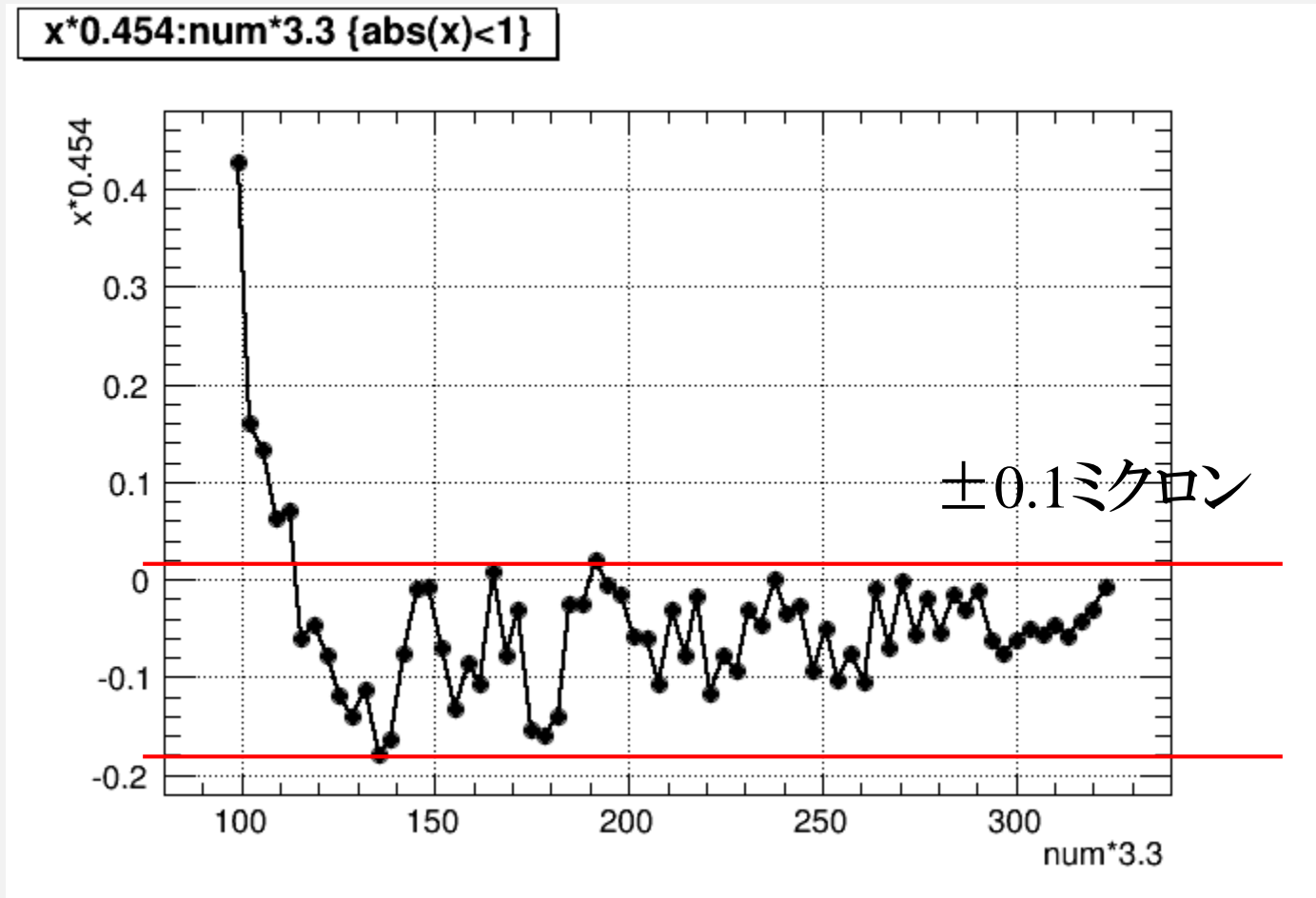
By optimizing the acceleration, 5view/sec was achieved.

The displacement has been measured by using main optics.





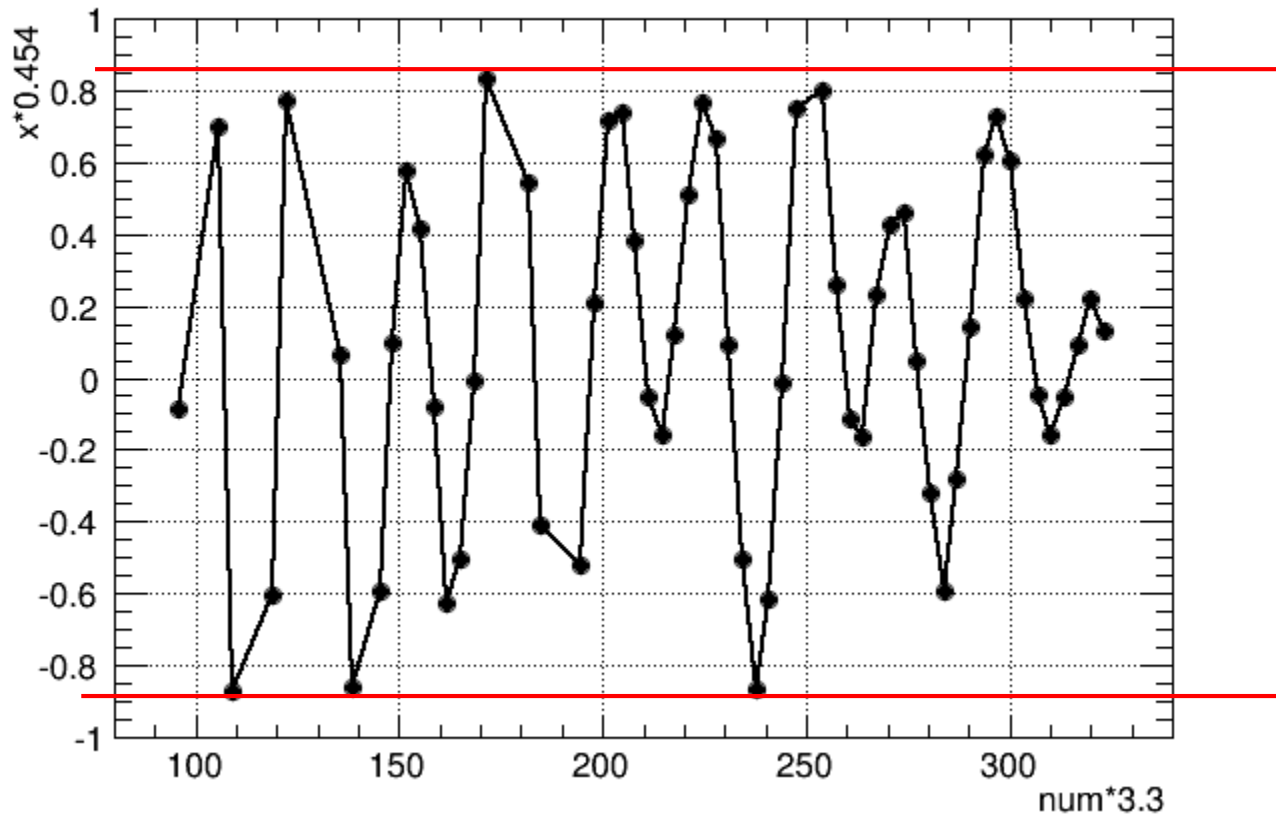
# 0.4G Acceleration and Stop : 115ms



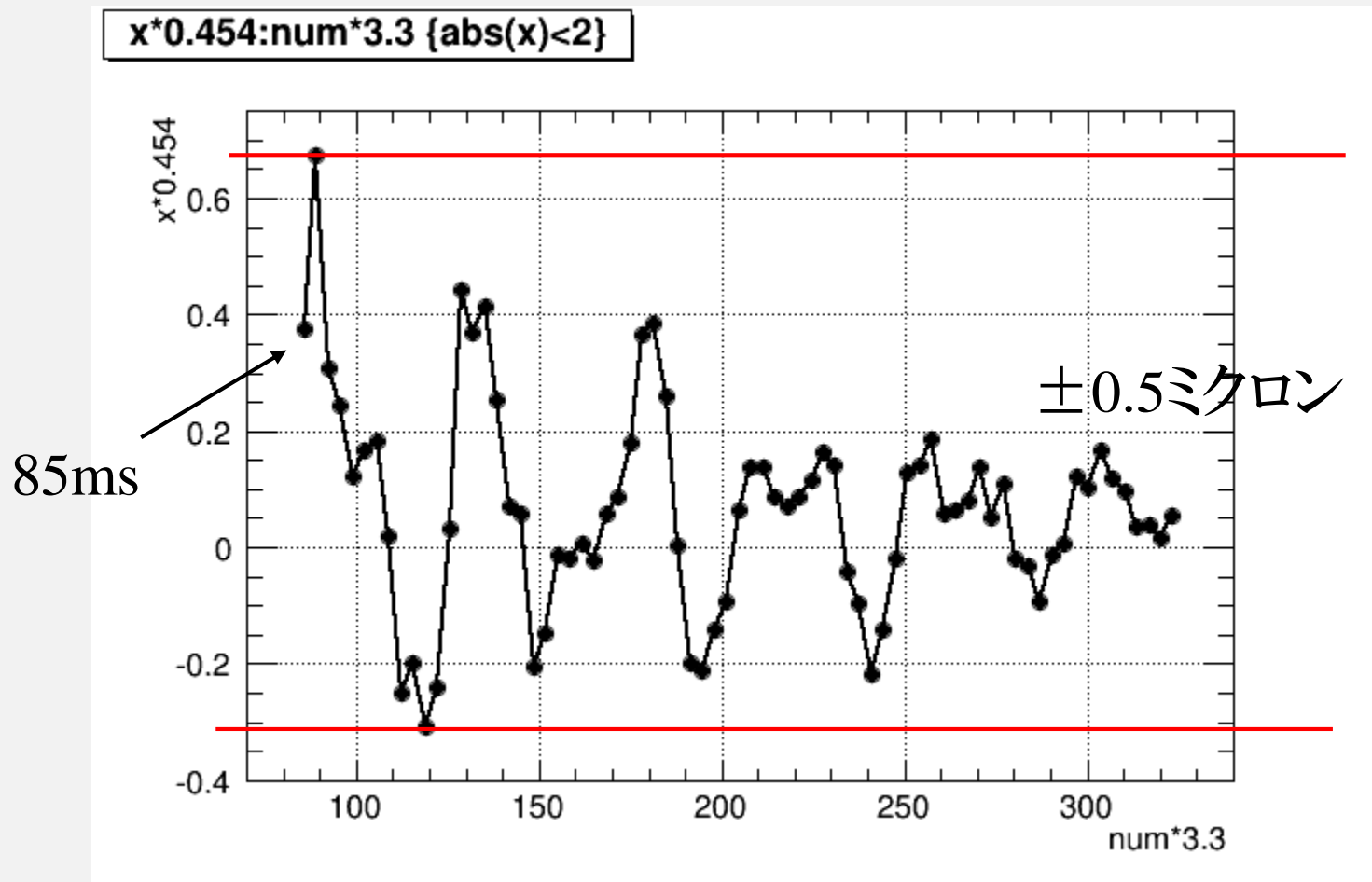
# 0.4G Acceleration and Stop without Counter Stage

$x \times 0.454 : \text{num} \times 3.3 \{ \text{abs}(x) < 2 \}$

±0.9ミクロン

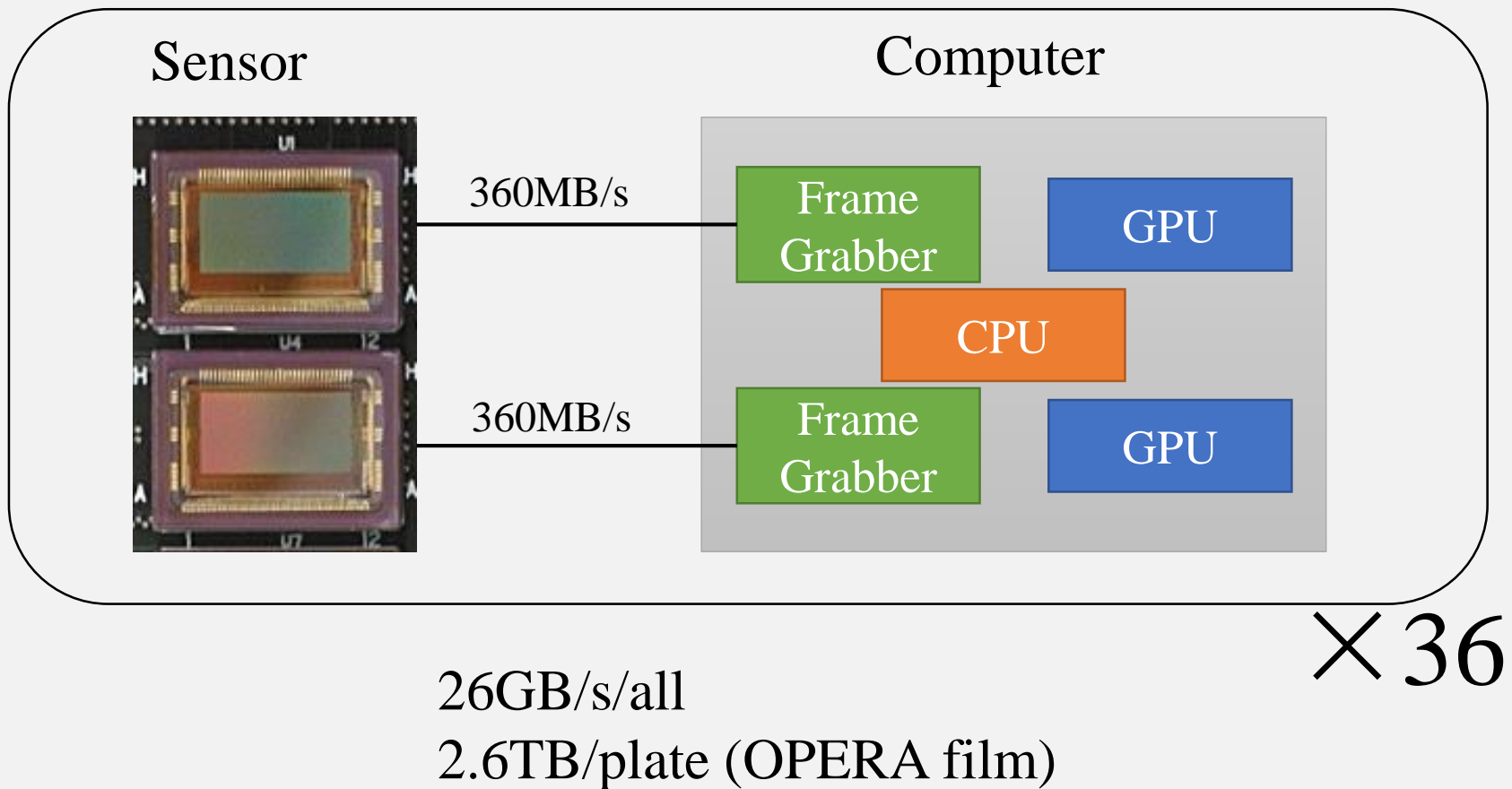


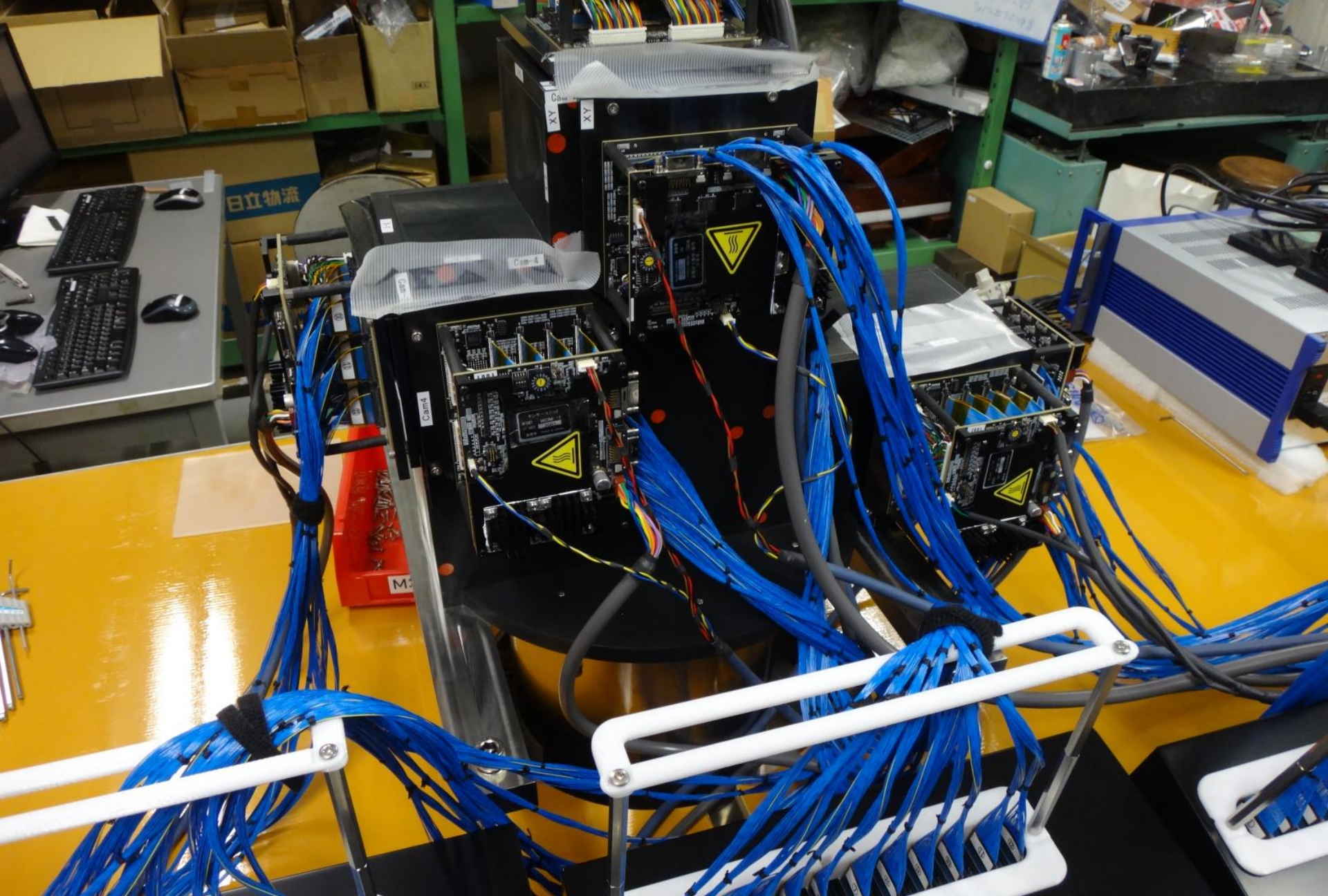
# 1.0G Acceleration and Stop (X-axis) : 85ms



# Imaging and Tracking

- Sensor  $72 \times 36\text{Mbyte/view} \times 10\text{view/s} = 26\text{GB/s}$
- Computer 36, Frame grabber board 72, GPU board 72





カメラモジュール 6ユニット (72センサー)



画像処理PC 36台 (GPU 72基)

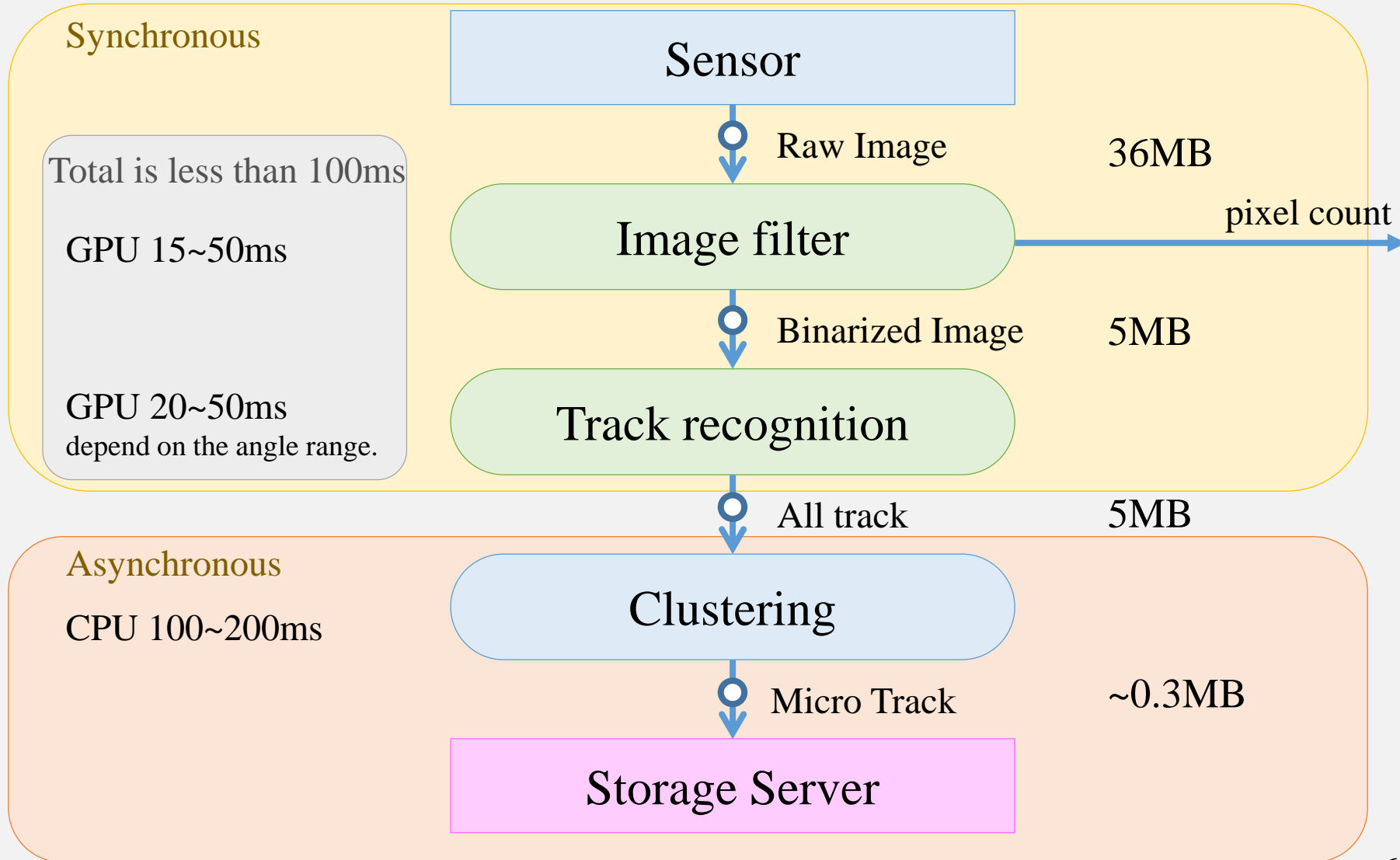


画像処理PC 36台 (GPU 72基)

# Image processing and Dataflow

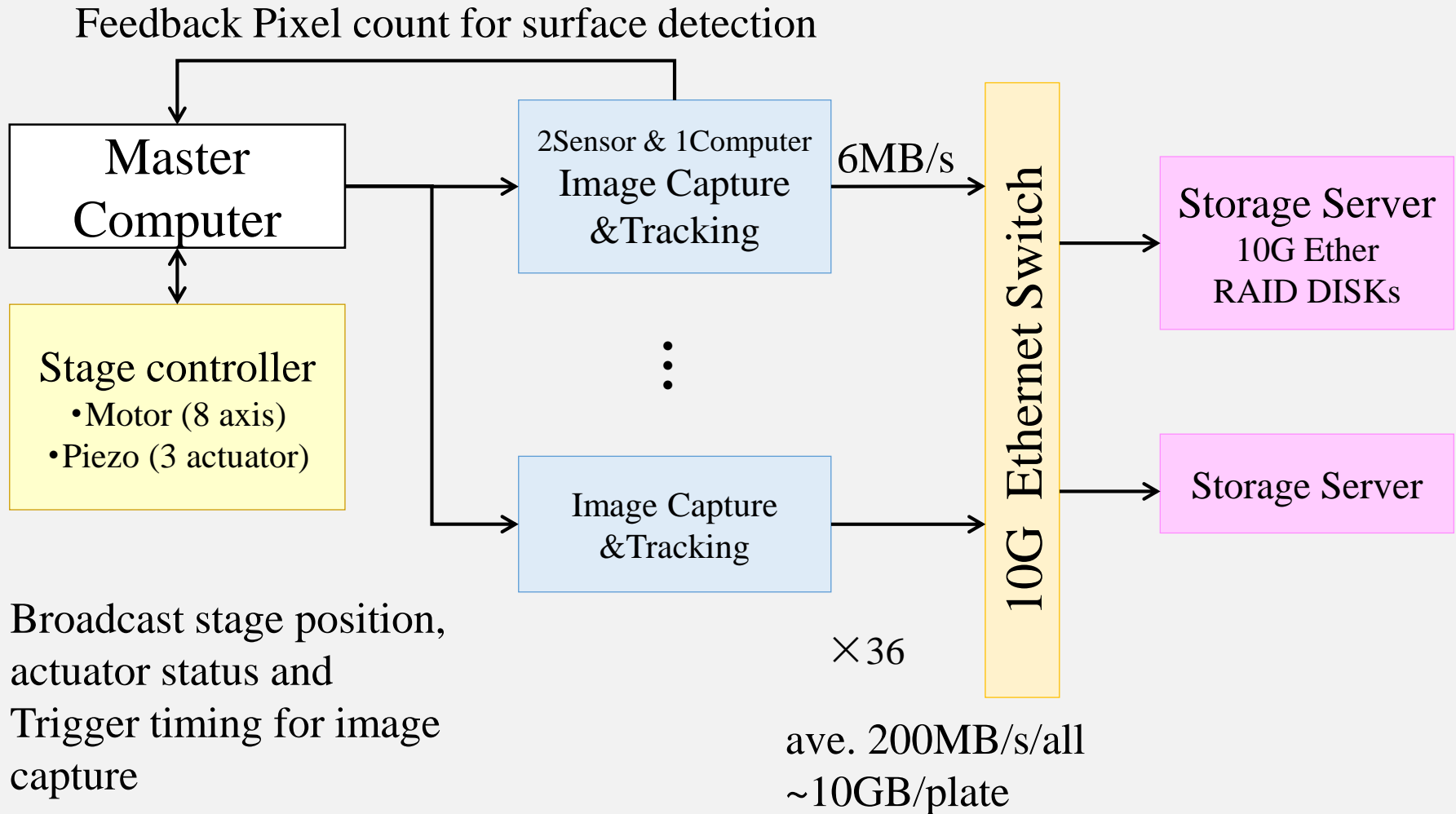
Amount of data  
per sensor per view

Processing time





# Stage control



Broadcast stage position,  
actuator status and  
Trigger timing for image  
capture



# New Emulsion Film

## HTS

efficiency

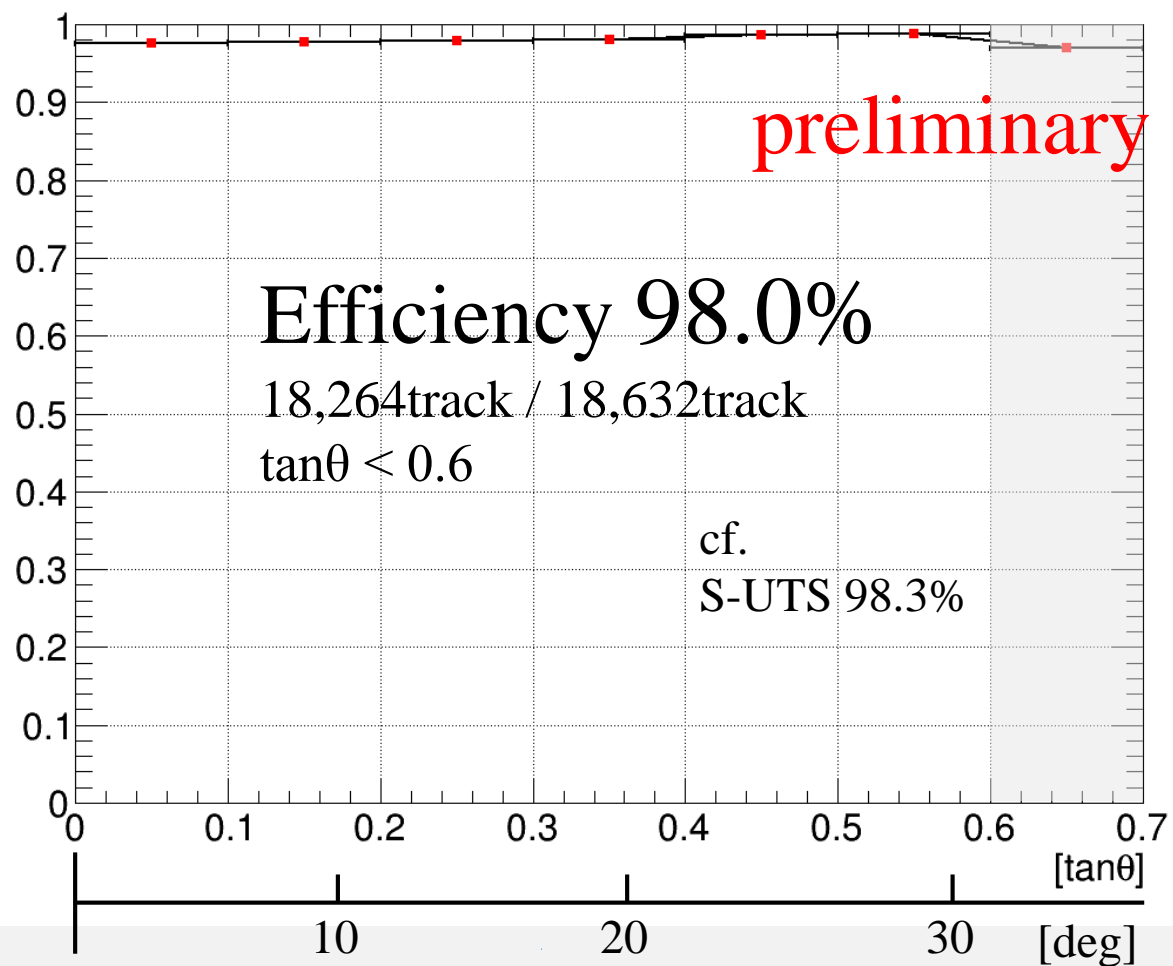
PL13

?

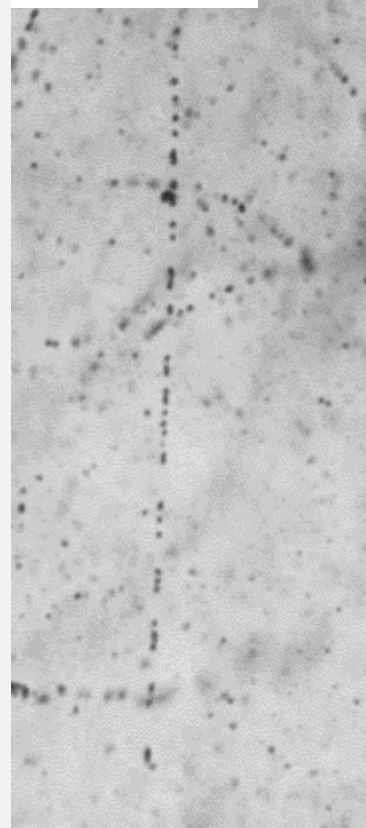
Exist or

PL11

not

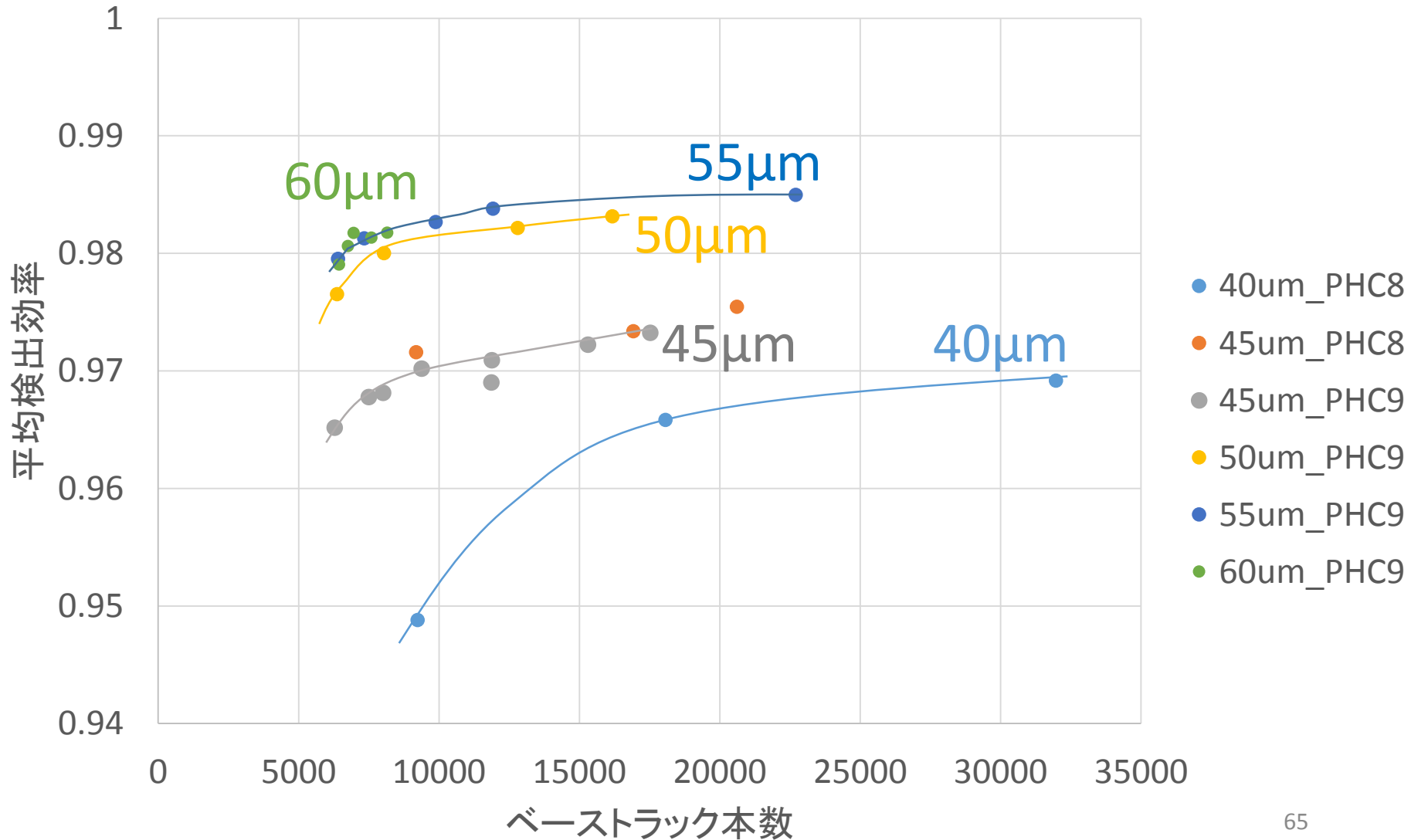


New type



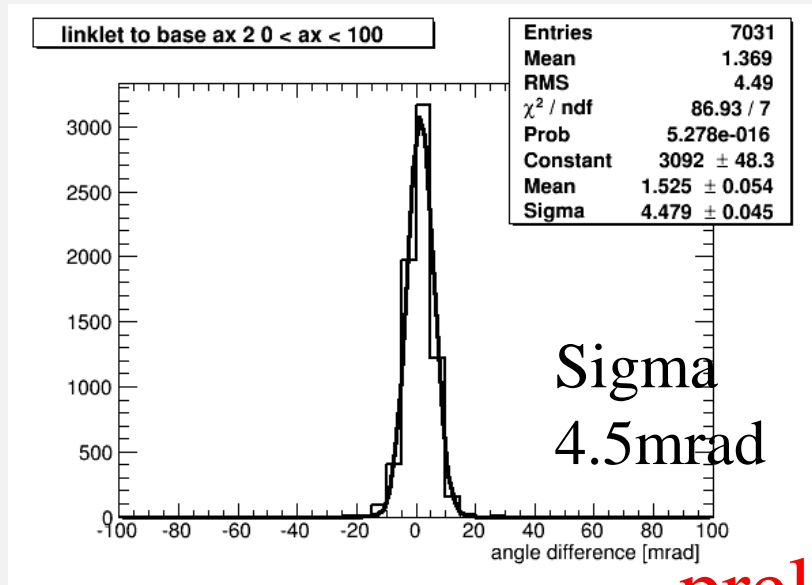
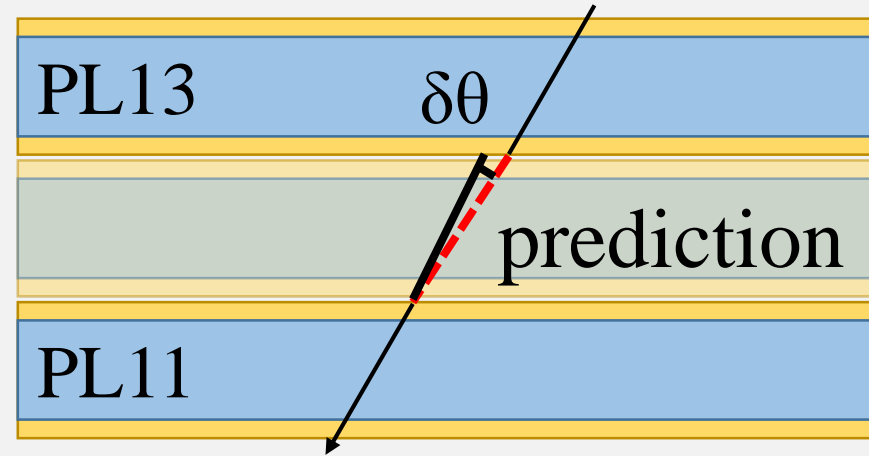
GD=51.6+-2.6  
FD=3.3+-0.4 64

# 検出効率とSNの評価



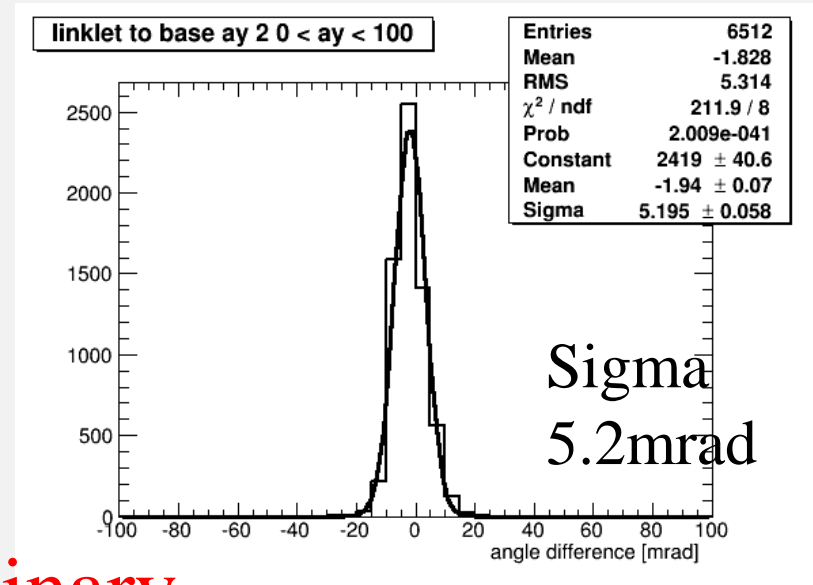
# New Emulsion Film

- Angle deviation



X-projection

cf. S-UTS  
4.8mrad



Y-projection

cf. S-UTS  
4.3mrad

preliminary

# 入射角度の大きい飛跡に対する角度分解能の改善

$$\delta(\Delta \tan \theta_x) = \frac{\sqrt{2}}{b} \sqrt{2\delta x^2 + \delta b^2 \cdot \tan^2 \theta_x}$$

Fitting parameter

$$\delta x = 0.28 \pm 0.04$$

$$\delta b = 2.68 \pm 0.09$$



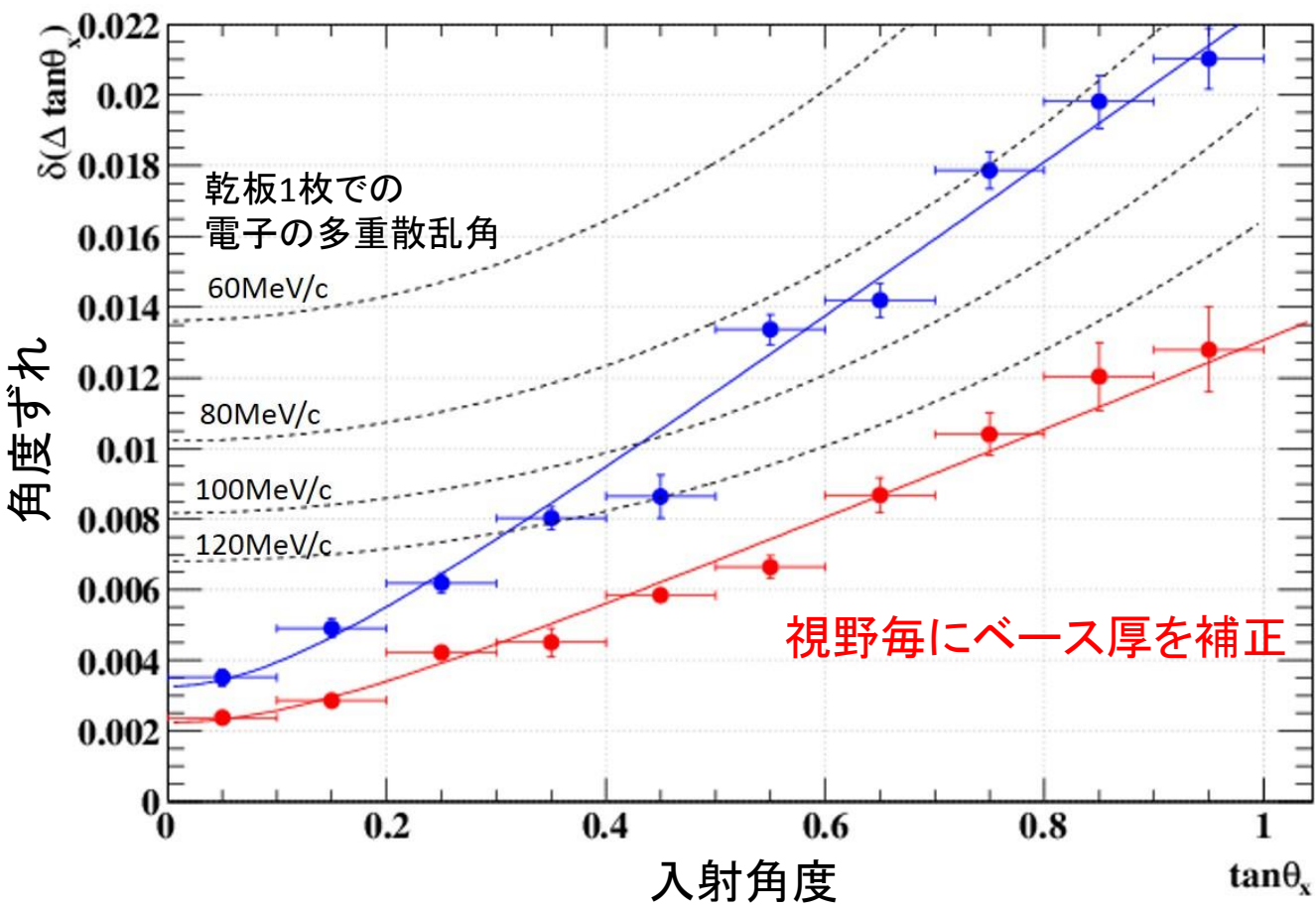
$$\delta x = 0.19 \pm 0.02$$

$$\delta b = 1.55 \pm 0.07$$

※  $\delta x$  の改善はカメラセンサー数の違い.

大角度飛跡の  
角度分解能が  
改善した.

※複数回の測定で  
さらに高精度化が可能.

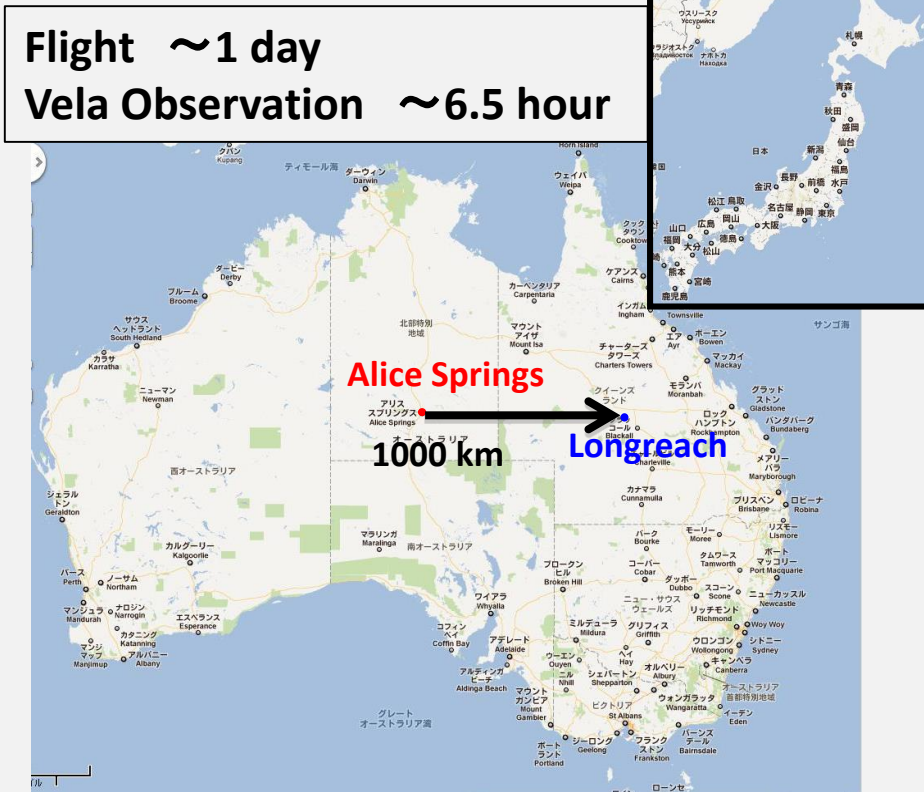
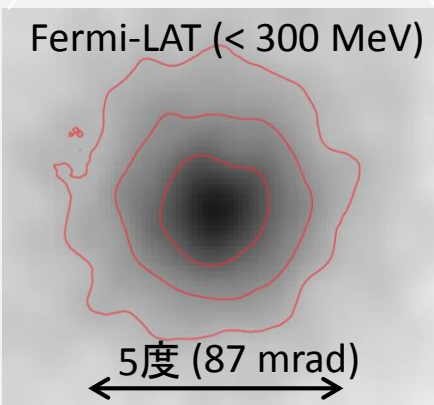
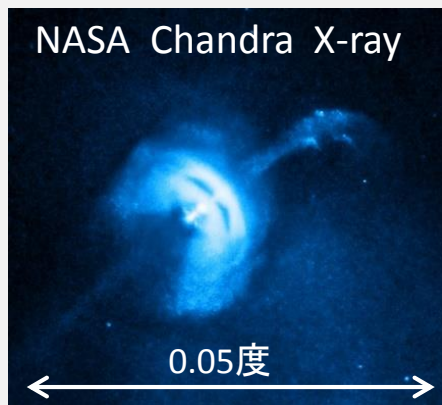
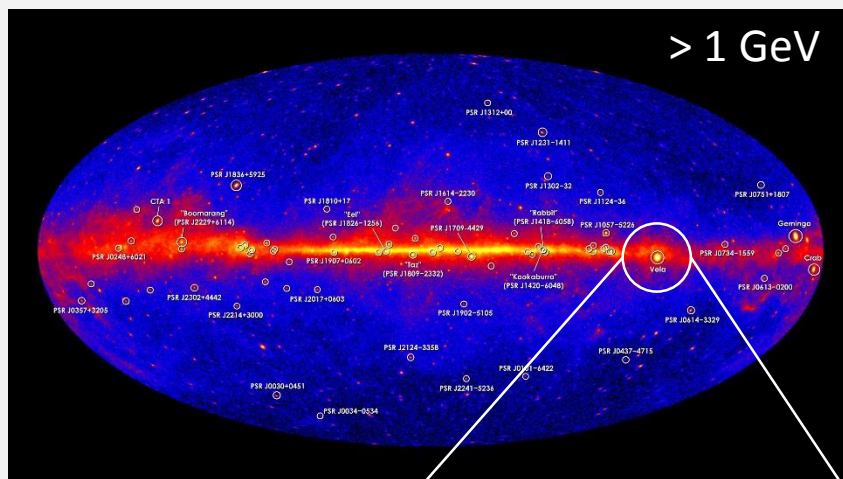


# Commissioning

# 2015 Australia Flight

Aim

Prove the angular resolution by observing Vela Pulsar  $0.5^\circ$   
( $\approx 10$  mrad) @100–300 MeV



Vela Pulsar ( $Flux \sim 1 \times 10^{-5} \text{ cm}^{-2} \text{ s}^{-1}$  @100MeV–10GeV)



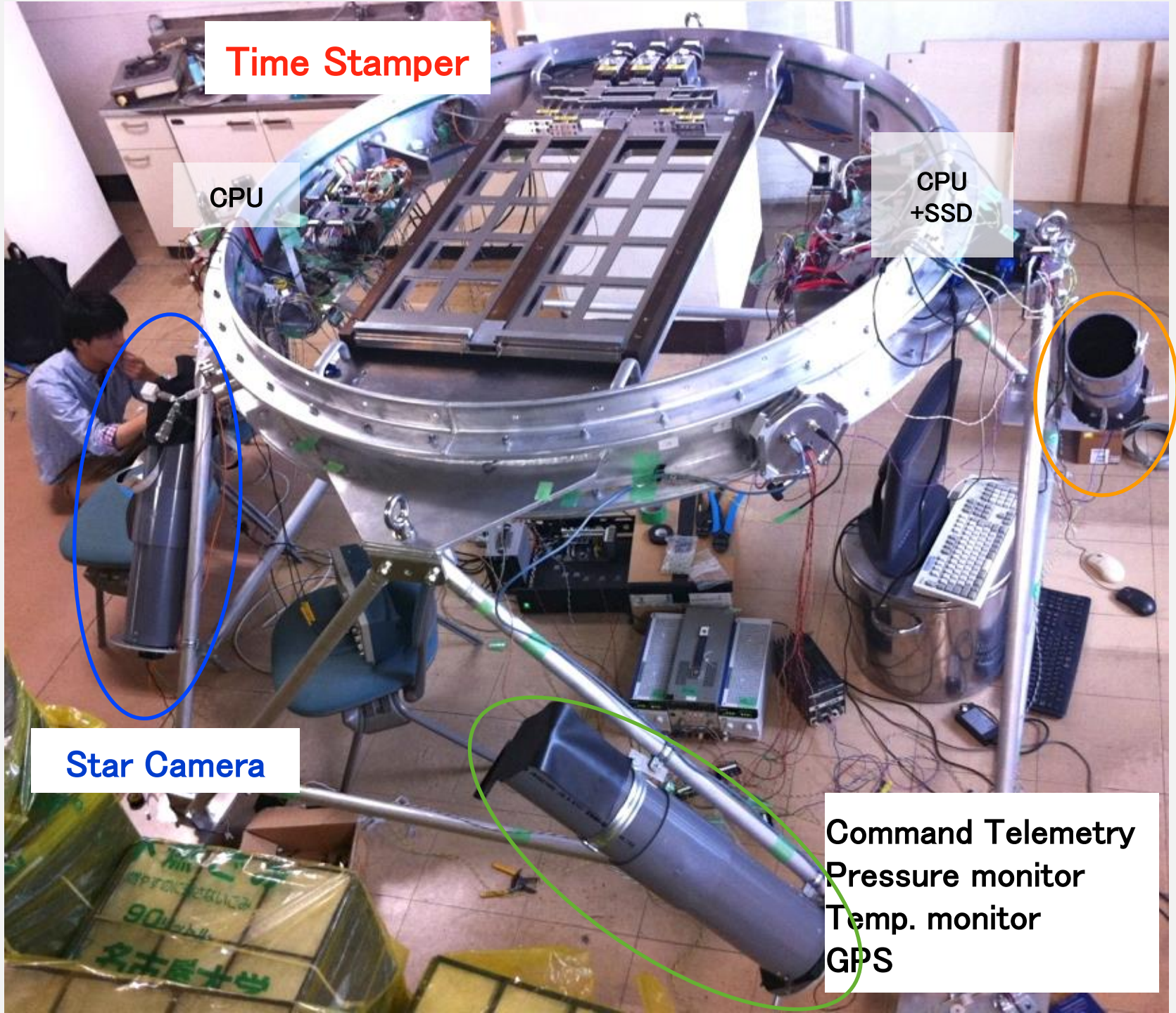
**Time Stamper**

**CPU**

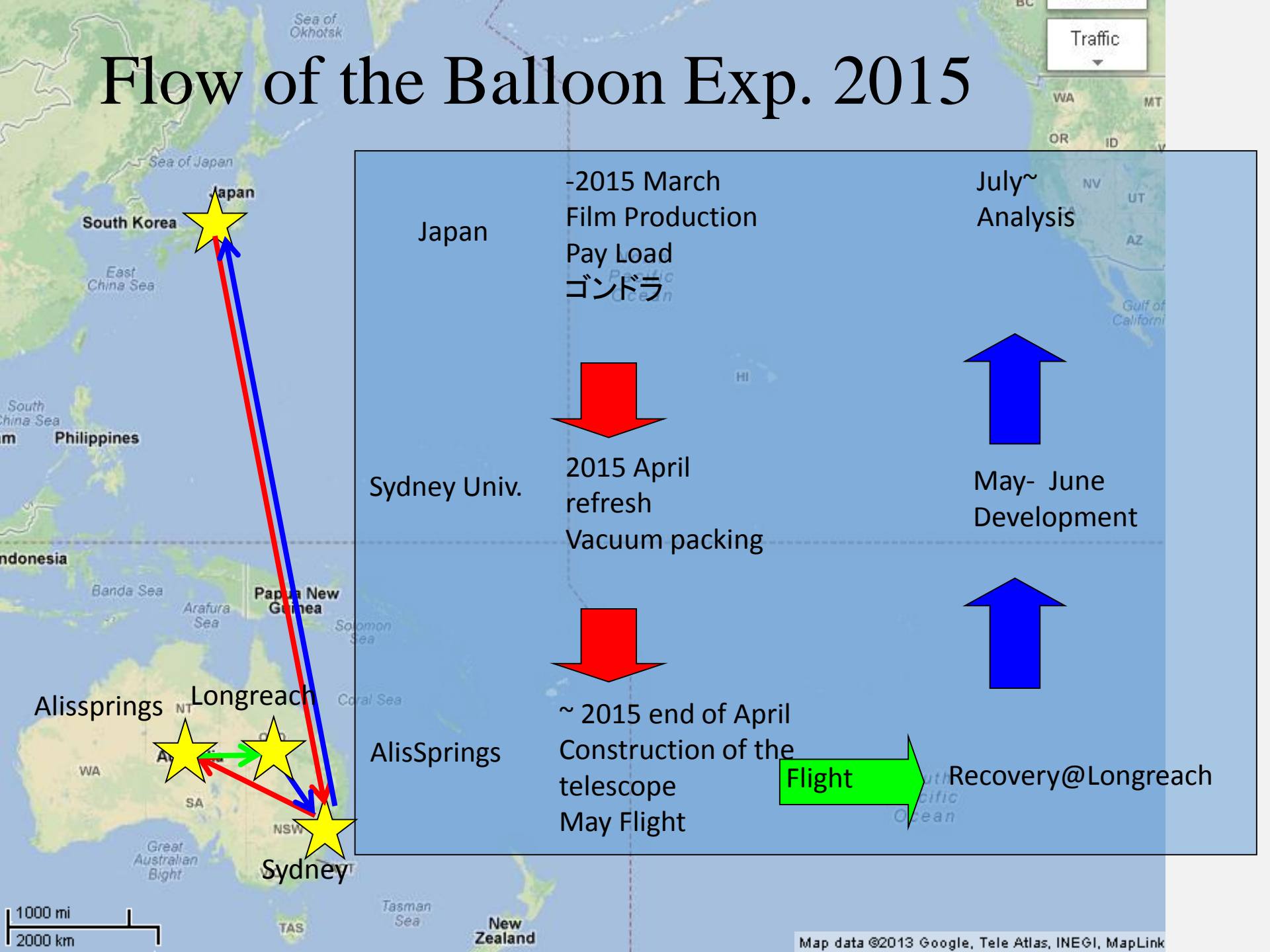
**CPU  
+SSD**

**Star Camera**

**Command Telemetry  
Pressure monitor  
Temp. monitor  
GPS**



# Flow of the Balloon Exp. 2015



1000 mi  
2000 km

# Summary and Prospect

- More Scanning Power is required.
- We are developing HTS which is 100 times faster.
- The efficiency and angle resolution are reasonably good (at the same level as the previous system).
- Commissioning of HTS will be started with GRAINE project.